

RTCA, Inc.  
1150 18<sup>th</sup> Street, N.W., Suite 910  
Washington, DC 20036  
USA

# **Minimum Operational Performance Standards for Global Positioning System/Satellite-Based Augmentation System Airborne Equipment**

**(Change 1, Appendix V,  
Integrated and Highlighted)**

RTCA DO-229D  
December 13, 2006  
Change 1  
February 1, 2013

Prepared by: SC-159  
©2013 RTCA, Inc

Copies of this document may be obtained from

RTCA, Inc.  
1150 18<sup>th</sup> Street, N.W., Suite 910  
Washington, DC 20036

Telephone: 202-333-9339  
Facsimile: 202-833-9434  
Internet: [www.rtca.org](http://www.rtca.org)

Please visit the RTCA Online Store for document pricing and ordering information

## FOREWORD

This document was prepared by Special Committee 159 (SC-159) and approved by the RTCA Program Management Committee on February 1, 2013.

RTCA, Incorporated is a not-for-profit corporation formed to advance the art and science of aviation and aviation electronic systems for the benefit of the public. The organization functions as a Federal advisory committee, and develops consensus-based recommendations on contemporary aviation issues. RTCA's objectives include but are not limited to:

- coalescing aviation system user and provider technical requirements in a manner that helps government and industry meet their mutual objectives and responsibilities;
- analyzing and recommending solutions to the system technical issues that aviation faces and it continues to pursue increased safety, system capacity and efficiency;
- developing consensus on the application of pertinent technology to fulfill user and provider requirements, including development of minimum operational performance standards for electronic systems and equipment that support aviation; and
- assisting in developing the appropriate technical material upon which positions for the International Civil Aviation Organization and the International Telecommunication Union and other appropriate international organizations can be based.

The organization's recommendations are often used as the basis for government and private sector decisions as well as the foundation for many Federal Aviation Administration Technical Standard Orders and several advisory circulars.

Since RTCA is not an official agency of the United States Government, its recommendations may not be regarded as statements of official government policy unless so enunciated by the U.S. government organization or agency having statutory jurisdiction over any matters to which the recommendations relate.

This Page Intentionally Left Blank

## TABLE OF CONTENTS

<b>1.0</b>	<b>PURPOSE AND SCOPE</b> .....	<b>1</b>
<b>1.1</b>	<b>Introduction</b> .....	<b>1</b>
<b>1.2</b>	<b>System Overview</b> .....	<b>3</b>
1.2.1	Wide Area Augmentation System.....	3
1.2.2	GNSS Satellite Signal Characteristics.....	4
1.2.2.1	GPS Signal Characteristics.....	4
1.2.2.2	WAAS Signal Characteristics.....	5
<b>1.3</b>	<b>Operational Goals</b> .....	<b>6</b>
1.3.1	Intended Operational Applications.....	6
1.3.2	Operational Environment.....	6
1.3.3	International Compatibility.....	7
<b>1.4</b>	<b>Equipment Classes</b> .....	<b>8</b>
1.4.1	Functional Classes.....	8
1.4.2	Operational Classes.....	9
1.4.3	Relation of Classes to Document Organization.....	10
<b>1.5</b>	<b>Aiding and Barometric Vertical Navigation</b> .....	<b>11</b>
1.5.1	SBAS and Barometric Vertical Navigation.....	11
1.5.2	Aiding of Fault Detection and Exclusion.....	12
<b>1.6</b>	<b>Test Considerations</b> .....	<b>12</b>
1.6.1	Environmental Tests.....	12
1.6.2	Bench Tests.....	12
<b>1.7</b>	<b>Definition of Key Terms</b> .....	<b>13</b>
1.7.1	General Terms.....	13
1.7.2	Alert Limits and Protection Levels.....	14
1.7.3	Fault Detection and Exclusion (FDE) Terms.....	15
<b>1.8</b>	<b>Assumptions and Approach to Selected Issues</b> .....	<b>20</b>
1.8.1	General.....	20
1.8.1.1	GPS Constellation and WAAS/SBAS Ground/Space Segments.....	20
1.8.1.2	GPS/SBAS Performance.....	20
1.8.1.3	Applicability.....	21
1.8.1.4	Interoperability.....	21
1.8.1.5	Integrity Monitoring.....	21
1.8.1.6	Navigation Waypoints.....	21
1.8.1.7	RF Interference.....	22
1.8.1.8	Time of Applicability of Information in the SBAS Signal-in-Space.....	22
1.8.1.9	Change of Broadcast Ephemeris.....	22
1.8.1.10	SBAS Regional Message Type (Message Type 27 and 28).....	22
1.8.2	Approach Applications.....	22
1.8.2.1	SBAS Performance for Approaches.....	22
1.8.2.2	Approach Path-in-Space.....	23
1.8.2.3	LNAV/VNAV, LP, LPV Approach Position Integrity.....	23
1.8.2.4	Vector-to-Final (VTF) Approach.....	24
<b>2.0</b>	<b>EQUIPMENT PERFORMANCE AND TEST PROCEDURES</b> .....	<b>25</b>
<b>2.1</b>	<b>General Requirements</b> .....	<b>25</b>
2.1.1	Requirements Applicable to Beta, Gamma, and Delta Equipment.....	25
2.1.1.1	General Requirements for All Navigation Modes.....	25
2.1.1.1.1	Airworthiness.....	25

2.1.1.1.2	General Performance .....	25
2.1.1.1.3	Fire Resistance .....	25
2.1.1.1.4	Equipment Interfaces .....	25
2.1.1.1.5	Effects of Test .....	25
2.1.1.2	GPS Signal Processing Requirements .....	26
2.1.1.3	SBAS Signal Processing Requirements .....	26
2.1.1.3.1	Acquisition and Track .....	26
2.1.1.3.2	Demodulation and Forward Error Correction (FEC) Decoding .....	27
2.1.1.3.3	SBAS Satellite Pseudorange Determination .....	27
2.1.1.4	SBAS Message Processing .....	27
2.1.1.4.1	Message Type 0 - Don't Use for Safety Applications .....	28
2.1.1.4.2	Message Type 1 - PRN Mask Assignments .....	28
2.1.1.4.3	Message Types 2-5 and 24 - Fast Corrections .....	28
2.1.1.4.4	Message Type 6 - Integrity Information .....	29
2.1.1.4.5	Message Type 7 - Fast Correction Degradation .....	30
2.1.1.4.6	Message Type 9 - SBAS Satellite Navigation Message .....	30
2.1.1.4.7	Message Type 17 - SBAS Satellite Almanac .....	30
2.1.1.4.8	Message Type 27 - SBAS Service Message .....	30
2.1.1.4.9	Message Timeout Periods .....	30
2.1.1.4.10	Combining Data from Separate Broadcasts .....	32
2.1.1.4.11	Message Type 24 and 25 Long-Term Corrections .....	32
2.1.1.4.12	Application of Differential Corrections .....	33
2.1.1.4.13	Message Type 28 - Clock-Ephemeris Covariance Matrix Message .....	34
2.1.1.5	Satellite Integrity Status .....	34
2.1.1.5.1	Step Detector .....	34
2.1.1.5.2	SBAS UNHEALTHY Designation .....	35
2.1.1.5.3	SBAS UNMONITORED Designation .....	35
2.1.1.5.4	SBAS HEALTHY Designation .....	35
2.1.1.5.5	GPS UNHEALTHY Designation .....	36
2.1.1.5.6	GPS HEALTHY Designation .....	36
2.1.1.6	Satellite Selection .....	36
2.1.1.7	Initial Acquisition Time .....	37
2.1.1.8	Satellite Acquisition Time .....	38
2.1.1.8.1	GPS Satellite Acquisition Time .....	38
2.1.1.8.2	SBAS Satellite Acquisition Time .....	38
2.1.1.9	Satellite Reacquisition Time .....	38
2.1.1.10	Sensitivity and Dynamic Range .....	39
2.1.1.11	Equipment Burnout Protection .....	40
2.1.1.12	Integrity in the Presence of Interference .....	41
2.1.1.13	Alerts/Outputs .....	41
2.1.1.13.1	Prognostic Level .....	41
2.1.1.13.2	Navigation Alert .....	42
2.1.2	Requirements for En Route and Terminal Mode .....	42
2.1.2.1	Accuracy .....	42
2.1.2.2	Integrity Requirements .....	42
2.1.2.2.1	Development Assurance .....	42
2.1.2.2.1.1	Hardware Compliance .....	43
2.1.2.2.1.2	Software Compliance .....	43
2.1.2.2.2	Integrity Monitoring .....	43
2.1.2.2.2.1	SBAS-Provided Integrity Monitoring .....	43
2.1.2.2.2.2	FDE-Provided Integrity Monitoring .....	43
2.1.2.2.2.2.1	Time-to-Alert .....	45
2.1.2.2.2.2.2	Missed Alert Probability .....	45
2.1.2.2.2.2.3	False Alert Probability .....	45
2.1.2.2.2.2.4	Failed Exclusion Probability .....	45
2.1.2.2.2.2.5	Availability .....	46

2.1.2.3	Equipment Reliability .....	46
2.1.2.4	Satellite Tracking Capability.....	46
2.1.2.5	Dynamic Tracking.....	46
2.1.2.6	Position Output .....	47
2.1.2.6.1	Position Output Data Update Rate .....	47
2.1.2.6.2	Position Output Data Latency .....	47
2.1.3	Requirements for LNAV .....	47
2.1.3.1	Accuracy .....	47
2.1.3.2	Integrity Requirements .....	47
2.1.3.2.1	Development Assurance .....	47
2.1.3.2.1.1	Hardware Compliance .....	47
2.1.3.2.1.2	Software Compliance.....	48
2.1.3.2.2	Integrity Monitoring.....	48
2.1.3.2.2.1	SBAS-Provided Integrity Monitoring.....	48
2.1.3.2.2.2	FDE-Provided Integrity Monitoring.....	48
2.1.3.2.2.2.1	Time-to-Alert .....	48
2.1.3.2.2.2.2	Missed Alert Probability .....	48
2.1.3.2.2.2.3	False Alert Probability .....	48
2.1.3.2.2.2.4	Failed Exclusion Probability .....	48
2.1.3.2.2.2.5	Availability.....	48
2.1.3.2.2.3	FD Prediction .....	49
2.1.3.3	Equipment Reliability .....	49
2.1.3.4	Satellite Tracking Capability.....	49
2.1.3.5	Dynamic Tracking.....	49
2.1.3.6	Position Output .....	50
2.1.3.6.1	Position Output Update Rate .....	50
2.1.3.6.2	Position Output Latency.....	50
2.1.3.7	SBAS Message Processing.....	50
2.1.3.8	Application of Differential Correction Term .....	50
2.1.3.9	Satellite Selection.....	50
2.1.4	Requirements for LNAV/VNAV Operations.....	50
2.1.4.1	Accuracy .....	50
2.1.4.1.1	Smoothing.....	50
2.1.4.1.2	Measurement Quality Monitoring.....	51
2.1.4.1.3	Accuracy .....	52
2.1.4.1.4	GPS Satellites .....	52
2.1.4.1.5	SBAS Satellites.....	53
2.1.4.1.6	Position Solution.....	53
2.1.4.2	Integrity Requirements .....	53
2.1.4.2.1	Development Assurance .....	53
2.1.4.2.1.1	Hardware Compliance .....	53
2.1.4.2.1.2	Software Compliance.....	53
2.1.4.2.2	Integrity Monitoring.....	53
2.1.4.2.2.1	SBAS-Provided Integrity Monitoring.....	54
2.1.4.2.2.2	Fault Detection-Provided Integrity Monitoring .....	54
2.1.4.2.2.2.1	Frequency of Fault Detection .....	54
2.1.4.2.2.2.2	Missed Alert.....	54
2.1.4.2.2.2.3	False Alert.....	54
2.1.4.2.2.2.4	Availability.....	54
2.1.4.3	Equipment Reliability .....	54
2.1.4.4	Satellite Tracking Capability.....	55
2.1.4.5	Tracking Constraints .....	55
2.1.4.5.1	GPS Tracking Constraints.....	55
2.1.4.5.2	SBAS Tracking Constraints .....	57
2.1.4.6	Correlation Peak Validation.....	58
2.1.4.7	Dynamic Tracking.....	58

2.1.4.8	Position Output .....	59
2.1.4.8.1	Position Output Update Rate .....	59
2.1.4.8.2	Position Output Latency.....	59
2.1.4.9	SBAS Message Processing.....	59
2.1.4.9.1	Message Type 2-5, 6 and 24 Fast Corrections .....	59
2.1.4.9.2	Message Types 24 and 25 Long-Term Corrections .....	59
2.1.4.9.3	Message Type 18 - Ionospheric Grid Point Masks .....	59
2.1.4.9.4	Message Type 26 - Ionospheric Grid Point Delays.....	59
2.1.4.9.5	Message Types 7 and 10 - Degradation Parameters .....	59
2.1.4.10	Application of Differential Correction Terms .....	60
2.1.4.10.1	Application of Clock and Ephemeris Corrections.....	60
2.1.4.10.2	Application of Ionospheric Corrections .....	60
2.1.4.10.3	Application of Tropospheric Corrections .....	60
2.1.4.11	Satellite Selection.....	60
2.1.4.12	Alerts/Outputs/Inputs .....	61
2.1.4.12.1	Protection Level.....	61
2.1.4.12.2	Navigation Alert .....	61
2.1.5	Requirements for LPV and LP Approach Operations .....	62
2.1.5.1	Accuracy .....	62
2.1.5.2	Integrity Requirements .....	62
2.1.5.2.1	Development Assurance .....	62
2.1.5.2.1.1	Hardware Compliance .....	62
2.1.5.2.1.2	Software Compliance.....	62
2.1.5.2.2	Integrity Monitoring.....	62
2.1.5.2.2.1	SBAS-Provided Integrity Monitoring.....	63
2.1.5.2.2.2	Fault Detection-Provided Integrity Monitoring.....	63
2.1.5.2.2.2.1	Frequency of Fault Detection .....	63
2.1.5.2.2.2.2	Missed Alert.....	63
2.1.5.2.2.2.3	False Alert.....	63
2.1.5.2.2.2.4	Availability.....	63
2.1.5.3	Equipment Reliability .....	63
2.1.5.4	Satellite Tracking Capability.....	64
2.1.5.5	Tracking Constraints .....	64
2.1.5.5.1	GPS Tracking Constraints .....	64
2.1.5.5.2	SBAS Tracking Constraints .....	64
2.1.5.6	Correlation Peak Validation .....	64
2.1.5.7	Dynamic Tracking.....	64
2.1.5.8	Position Output .....	64
2.1.5.8.1	Position Output Update Rate .....	64
2.1.5.8.2	Position Output Latency.....	64
2.1.5.9	SBAS Message Processing.....	65
2.1.5.9.1	Message Type 2-5, 6 and 24 Fast Corrections .....	65
2.1.5.9.2	Message Types 24 and 25 Long-Term Corrections .....	65
2.1.5.9.3	Message Type 18 - Ionospheric Grid Point Masks .....	65
2.1.5.9.4	Message Type 26 - Ionospheric Grid Point Delays.....	65
2.1.5.9.5	Message Types 7 and 10 - Degradation Parameters .....	65
2.1.5.10	Application of Differential Correction Terms .....	65
2.1.5.11	Satellite Selection.....	65
2.1.5.12	Alerts/Outputs/Inputs .....	65
2.1.5.12.1	Protection Level.....	65
2.1.5.12.2	Navigation Alert .....	66
2.1.5.13	HPL and VPL Prediction .....	66
<b>2.2</b>	<b>Class Gamma Requirements.....</b>	<b>67</b>
2.2.1	Class Gamma General Requirements.....	67
2.2.1.1	General Human Factors Requirements and Applicable Documents.....	67
2.2.1.1.1	Controls .....	68

2.2.1.1.1.1	Operation	68
2.2.1.1.1.2	Control Labels	68
2.2.1.1.2	Equipment Operating Procedures	68
2.2.1.1.3	Minimum Workload Functions	68
2.2.1.1.4	Displays	70
2.2.1.1.4.1	Discernability	70
2.2.1.1.4.2	Brightness, Contrast, and Color	71
2.2.1.1.4.3	Angle of Regard	71
2.2.1.1.4.4	Symbology	71
2.2.1.1.4.5	Alphanumerics	71
2.2.1.1.4.6	Moving Map	73
2.2.1.1.4.7	Primary Navigation Display	73
2.2.1.1.4.8	Bearing Labels	73
2.2.1.1.5	Annunciations	73
2.2.1.1.5.1	Annunciators	74
2.2.1.1.5.2	Messages	74
2.2.1.1.6	Set of Standard Function Labels	74
2.2.1.1.7	Set of Standard Abbreviations and Acronyms	75
2.2.1.2	Path Selection	78
2.2.1.2.1	Flight Plan Selection	78
2.2.1.2.2	Flight Plan Review	78
2.2.1.2.3	Flight Plan Activation	79
2.2.1.2.4	Waypoint Sequencing	79
2.2.1.2.5	Manually-Selected Active Waypoint	79
2.2.1.2.5.1	Direct To	79
2.2.1.2.5.2	TO/FROM Course Selection	79
2.2.1.2.5.3	Manually-Selected Waypoint and Waypoint Sequencing	80
2.2.1.2.6	User-Defined Waypoints	80
2.2.1.2.7	Emergency Procedures	80
2.2.1.3	Path Definition	80
2.2.1.3.1	Initial Fix (IF)	81
2.2.1.3.2	Fixed Waypoint to a Fixed Waypoint (TF)	81
2.2.1.3.3	DME Arcs (AF) and Constant Radius to a Fix (RF)	81
2.2.1.3.4	Direct To (DF)	82
2.2.1.3.5	Course to a Fix Waypoint (CF)	83
2.2.1.3.6	FROM Leg	83
2.2.1.3.7	Fly-By Turns	83
2.2.1.3.7.1	Fly-By Turn Applications	84
2.2.1.3.7.2	Fly-By Theoretical Transition Area	84
2.2.1.3.7.3	Accepted Means of Defining Fly-By Turns	85
2.2.1.3.8	Fly Over Turns	86
2.2.1.3.9	Fixed Radius Turns	86
2.2.1.3.10	Waypoint Sequencing	86
2.2.1.3.11	Holding Patterns / Procedure Turns	87
2.2.1.3.12	Magnetic Course	88
2.2.1.3.13	Dead Reckoning	88
2.2.1.3.14	Fuel Management and Alerting	88
2.2.1.3.15	Geodesic Path Computation Accuracy	89
2.2.1.3.16	Parallel Offsets	89
2.2.1.4	Navigation Displays	90
2.2.1.4.1	Primary Navigation Display	90
2.2.1.4.2	Non-Numeric Display/Output Characteristics	90
2.2.1.4.2.1	Electrical Output	90
2.2.1.4.2.2	Display	91
2.2.1.4.3	Active Waypoint Distance Display	91
2.2.1.4.4	Active Waypoint Bearing Display	91

2.2.1.4.5	Track Displays .....	92
2.2.1.4.5.1	Desired Track .....	92
2.2.1.4.5.2	Track Angle .....	92
2.2.1.4.5.3	Track Angle Error .....	92
2.2.1.4.6	Display of TO or FROM Operation .....	92
2.2.1.4.7	Waypoint Bearing/Distance Display .....	92
2.2.1.4.8	Estimate of Position Uncertainty .....	92
2.2.1.4.9	Magnetic Course .....	92
2.2.1.4.10	Ground Speed .....	92
2.2.1.4.11	Aircraft Present Position .....	93
2.2.1.5	Database Requirements .....	93
2.2.1.5.1	Access .....	93
2.2.1.5.2	Content .....	93
2.2.1.5.3	Database Standard .....	94
2.2.1.5.4	Reference Coordinate System .....	94
2.2.1.5.4.1	Incorporation of Conversion Algorithms .....	94
2.2.1.5.4.2	Operational Approval .....	94
2.2.1.6	Alerts/Outputs .....	95
2.2.1.6.1	Caution Associated with Loss of Integrity Monitoring .....	95
2.2.1.6.2	Caution Associated with Loss of Navigation .....	95
2.2.1.7	Mode Switching Requirements .....	95
2.2.2	Class Gamma Requirements for En Route / Terminal Operation .....	99
2.2.2.1	General Human Factors Requirements .....	99
2.2.2.2	Path Selection .....	99
2.2.2.3	Path Definition .....	99
2.2.2.4	Navigation Displays .....	99
2.2.2.4.1	Primary Navigation Displays .....	99
2.2.2.4.2	Non-Numeric Cross-Track Deviation .....	100
2.2.2.4.3	Numeric Cross-Track Deviation .....	100
2.2.2.4.4	Displayed Data Update Rate .....	100
2.2.2.4.5	Display Update Latency .....	100
2.2.2.5	Database Requirements .....	100
2.2.2.6	Alerts .....	100
2.2.2.6.1	Alert Limits .....	100
2.2.2.6.2	Caution Associated with Loss of Integrity Monitoring .....	100
2.2.2.6.3	Caution Associated with Loss of Navigation .....	101
2.2.2.7	En Route / Terminal Mode Switching Requirements .....	101
2.2.2.7.1	En Route Mode Switching Requirements .....	101
2.2.2.7.1.1	Entry Criteria .....	101
2.2.2.7.1.2	Exit Criteria .....	102
2.2.2.7.1.3	Display Transition Requirements .....	102
2.2.2.7.2	Terminal Mode Switching Requirements .....	102
2.2.2.7.2.1	Entry Criteria .....	102
2.2.2.7.2.2	Exit Criteria .....	102
2.2.2.7.2.3	Display Transition Requirements .....	102
2.2.3	Class Gamma Requirements for LNAV Approach Operation .....	102
2.2.3.1	General Human Factors Requirements .....	102
2.2.3.2	Path Selection .....	102
2.2.3.2.1	Approach Selection .....	103
2.2.3.2.2	Missed Approach Sequencing .....	103
2.2.3.3	Path Definition .....	103
2.2.3.3.1	Approach Path Definition .....	103
2.2.3.3.2	Missed Approach Path Definition .....	105
2.2.3.3.3	Departure Path Definition .....	106
2.2.3.3.4	Vertical Path for LNAV Procedures .....	106
2.2.3.4	Navigation Displays .....	107

2.2.3.4.1	Primary Navigation Displays .....	107
2.2.3.4.2	Non-Numeric Cross-Track Deviation .....	107
2.2.3.4.3	Numeric Cross-Track Deviation .....	107
2.2.3.4.4	Missed Approach Waypoint Distance Display .....	108
2.2.3.4.5	Missed Approach Waypoint Bearing Display .....	108
2.2.3.4.6	Displayed Data Update Rate .....	108
2.2.3.4.7	Display Update Latency .....	108
2.2.3.5	Database Requirements .....	108
2.2.3.6	Alerts .....	109
2.2.3.6.1	Alert Limits .....	109
2.2.3.6.2	Caution Associated with Loss of Integrity Monitoring .....	109
2.2.3.6.3	Caution Associated with Loss of Navigation .....	109
2.2.3.7	Mode Switching Requirements .....	110
2.2.3.7.1	LNAV Approach Mode Switching Requirements .....	110
2.2.3.7.1.1	Entry Criteria .....	110
2.2.3.7.1.2	Exit Criteria .....	110
2.2.3.7.1.3	Display Transition Requirements .....	110
2.2.3.7.2	Departure Requirements .....	111
2.2.3.7.2.1	Entry Criteria .....	111
2.2.3.7.2.2	Exit Criteria .....	111
2.2.3.7.2.3	Display Transition Requirements .....	111
2.2.4	Class Gamma Requirements for LNAV/VNAV Operations .....	111
2.2.4.1	General Human Factors Requirements .....	111
2.2.4.2	Path Selection .....	111
2.2.4.2.1	5-Digit Channel Selection .....	111
2.2.4.2.2	Approach Selection .....	112
2.2.4.2.3	Missed Approach Sequencing .....	112
2.2.4.2.4	Deselection of Vertical Guidance .....	112
2.2.4.3	Path Definition .....	112
2.2.4.3.1	Approach Path Definition .....	112
2.2.4.3.2	Missed Approach Path Definition .....	113
2.2.4.3.3	Navigation Center Offset .....	113
2.2.4.4	Navigation Displays .....	113
2.2.4.4.1	Primary Navigation Displays .....	113
2.2.4.4.2	Non-Numeric Lateral Cross-Track Deviation .....	114
2.2.4.4.2.1	Definition of Final Approach Segment Lateral deviations .....	114
2.2.4.4.2.2	Non-VTF Deviation with FAS Data Block .....	114
2.2.4.4.2.3	VTF Deviation with FAS Data Block .....	115
2.2.4.4.2.4	Deviation without FAS Data Block .....	115
2.2.4.4.2.5	Missed Approach Deviation .....	115
2.2.4.4.3	Numeric Lateral Cross-Track Deviation .....	116
2.2.4.4.4	Non-Numeric Vertical Deviation .....	116
2.2.4.4.5	Missed Approach Waypoint/LTP/FTP Distance Display .....	118
2.2.4.4.6	Missed Approach Waypoint/LTP/FTP Bearing Display .....	118
2.2.4.4.7	Displayed Data Update Rate .....	118
2.2.4.4.8	Display Update Latency .....	119
2.2.4.4.9	Display of Vertical Accuracy .....	119
2.2.4.5	Database Requirements .....	119
2.2.4.5.1	Content .....	119
2.2.4.5.2	Data Integrity .....	120
2.2.4.6	Alerts .....	120
2.2.4.6.1	Alert Limits .....	120
2.2.4.6.2	Caution Associated with Loss of Integrity Monitoring .....	120
2.2.4.6.3	Caution Associated with Loss of Navigation .....	121
2.2.4.6.4	Low Altitude Alert .....	122
2.2.4.6.5	Alerting Scheme .....	122

2.2.4.7	LNAV/VNAV Approach Mode Switching Requirements .....	122
2.2.4.7.1	Entry Criteria .....	122
2.2.4.7.2	Exit Criteria .....	123
2.2.4.7.3	Display Transition.....	123
2.2.4.7.4	Advisory of LNAV/VNAV Availability .....	123
2.2.5	Class Gamma Requirements for LP and LPV Approach Operations .....	123
2.2.5.1	General Human Factors Requirements .....	123
2.2.5.2	Path Selection.....	124
2.2.5.2.1	5-Digit Channel Selection .....	124
2.2.5.2.2	Approach Name Selection .....	124
2.2.5.2.3	Missed Approach Sequencing.....	124
2.2.5.2.4	Selection of the Approach Type.....	124
2.2.5.3	Path Definition .....	125
2.2.5.3.1	Approach Path Definition .....	125
2.2.5.3.2	Missed Approach Path Definition.....	125
2.2.5.3.3	Navigation Center Offset .....	125
2.2.5.4	Navigation Displays .....	125
2.2.5.4.1	Primary Navigation Displays .....	125
2.2.5.4.2	Non-Numeric Lateral Cross-Track Deviation.....	125
2.2.5.4.2.1	Definition of Final Approach Segment Lateral Deviations.....	125
2.2.5.4.2.2	Non-VTF Deviation.....	125
2.2.5.4.2.3	VTF Deviation.....	125
2.2.5.4.2.4	Missed Approach Deviation .....	125
2.2.5.4.3	Numeric Lateral Cross-Track Deviation .....	125
2.2.5.4.4	Non-Numeric Vertical Deviation .....	125
2.2.5.4.5	Missed Approach Waypoint/LTP/FTP Distance Display .....	125
2.2.5.4.6	Missed Approach Waypoint/LTP/FTP Bearing Display.....	125
2.2.5.4.7	Displayed Data Update Rate .....	126
2.2.5.4.8	Display Update Latency.....	126
2.2.5.4.9	Display of Vertical Accuracy.....	126
2.2.5.5	Database Requirements .....	126
2.2.5.5.1	Content.....	126
2.2.5.5.2	Data Integrity .....	127
2.2.5.6	Alerts.....	127
2.2.5.6.1	Alert Limits.....	127
2.2.5.6.2	Caution Associated with Loss of Integrity Monitoring .....	127
2.2.5.6.3	Caution Associated with Loss of Navigation .....	127
2.2.5.6.4	Low Altitude Alert.....	129
2.2.5.6.5	Alerting Scheme.....	129
2.2.5.7	LP/LPV Approach Mode Switching Requirements.....	129
2.2.5.7.1	Entry Criteria .....	129
2.2.5.7.2	Exit Criteria .....	129
2.2.5.7.3	Display Transition.....	129
2.2.5.7.4	Advisory of LPV, LP Availability .....	130
<b>2.3</b>	<b>Class Delta-4 Requirements for Approach Operations .....</b>	<b>130</b>
2.3.1	General Human Factors Requirements.....	130
2.3.2	Approach Selection.....	130
2.3.2.1	Confirmation of Selected Approach.....	131
2.3.3	Path Definition .....	131
2.3.3.1	Navigation Center Offset.....	131
2.3.4	Navigation Displays.....	131
2.3.4.1	Non-Numeric Lateral Cross-Track Deviation .....	131
2.3.4.2	Non-Numeric Vertical Deviation .....	131
2.3.4.3	Landing Threshold Point/Fictitious Threshold Point Distance Display .....	132
2.3.4.4	Data Update Rate .....	132
2.3.4.5	Data Update Latency.....	132

2.3.5	Database Requirements.....	132
2.3.5.1	Content.....	132
2.3.5.2	Access.....	132
2.3.6	Alerts.....	133
2.3.6.1	Alert Limits.....	133
2.3.6.2	Caution Associated with Loss of Navigation.....	133
<b>2.4</b>	<b>Airborne Equipment Performance - Environmental Conditions .....</b>	<b>134</b>
2.4.1	Environmental Tests.....	135
2.4.1.1	Required Performance.....	135
2.4.1.1.1	Accuracy.....	135
2.4.1.1.2	Loss of Navigation Indication.....	136
2.4.1.1.3	Loss of Integrity Indication.....	136
2.4.1.1.4	Initial Acquisition Test.....	136
2.4.1.1.5	Sensitivity and Dynamic Range.....	136
2.4.1.1.6	Navigation Display.....	136
2.4.1.1.7	Database.....	136
2.4.1.1.8	Mode Annunciation.....	136
2.4.1.1.9	TO-TO and TO-FROM Capability.....	136
2.4.1.1.10	System Operating.....	136
2.4.1.2	Clarification of Environmental Tests.....	136
2.4.1.2.1	Power Input Tests.....	137
2.4.1.2.2	Icing Tests.....	137
2.4.1.2.3	RF and Induced Signal Susceptibility Tests.....	137
2.4.1.2.4	Lightning Induced Transient Susceptibility Tests.....	137
2.4.1.2.5	Lightning Direct Effects Tests.....	138
2.4.1.2.6	Crash Safety Shock.....	138
<b>2.5</b>	<b>Test Methods and Procedures .....</b>	<b>147</b>
2.5.1	Test Cross Reference Matrix.....	149
2.5.2	SBAS Message Loss Rate Test.....	227
2.5.2.1	Evaluation of Message Loss Rate During the Measurement Accuracy Test.....	227
2.5.2.2	Test Procedure.....	227
2.5.2.3	Pass/Fail Determination.....	227
2.5.2.4	Evaluation of Message Loss Rate During the 24-Hour System Accuracy Test.....	227
2.5.2.4.1	Test Procedure.....	227
2.5.2.4.2	Pass/Fail Criteria.....	227
2.5.3	Step Detector Test.....	227
2.5.3.1	Verification of Step Detector Operation Without Exclusion Capability.....	228
2.5.3.2	Verification of No Interference with Fault Detection Algorithm.....	228
2.5.3.3	Verification of Step Detector Operation with Exclusion Capability.....	228
2.5.3.4	Verification of No Interference with Exclusion of the FDE Algorithm.....	229
2.5.4	Initial Acquisition Test Procedures.....	229
2.5.4.1	Simulator and Interference Conditions.....	229
2.5.4.2	Test Procedures (Initial Acquisition).....	230
2.5.4.3	Pass/Fail Determination.....	230
2.5.4.4	Test Procedures (Initial Acquisition After Abnormal Interference).....	231
2.5.5	Reserved.....	232
2.5.6	Satellite Reacquisition Time Test.....	232
2.5.6.1	Simulator and Interference Conditions.....	232
2.5.6.2	Test Procedures.....	233
2.5.6.3	Pass/Fail Determination.....	234
2.5.7	Interference Rejection Test.....	234
2.5.7.1	Simulator and Interference Conditions.....	234
2.5.7.2	Test Procedures.....	234
2.5.7.3	Pass/Fail Determination.....	235
2.5.8	Accuracy Tests.....	235

2.5.8.1	Measurement Accuracy Test.....	235
2.5.8.2	Simulator and Interference Conditions.....	236
2.5.8.2.1	Test Procedures.....	237
2.5.8.3	24-Hour Actual Satellite Accuracy Test.....	240
2.5.8.3.1	Test Procedure.....	240
2.5.8.3.2	Pass/Fail Criteria.....	240
2.5.8.4	SBAS Tracking Bias.....	240
2.5.9	Integrity Monitoring Test Procedures.....	241
2.5.9.1	General Test Conditions.....	241
2.5.9.1.1	Test Philosophy.....	241
2.5.9.1.2	GPS Constellation.....	241
2.5.9.1.3	Applicability of RTCA/DO-178B.....	241
2.5.9.1.4	Test Repetition.....	241
2.5.9.1.5	Protection Level/Alert Limit.....	242
2.5.9.1.6	Time-to-Alert.....	242
2.5.9.2	Availability Tests.....	242
2.5.9.3	Off-Line FDE Tests.....	245
2.5.9.3.1	Off-Line Test Setup.....	245
2.5.9.3.2	Selection of Geometries.....	245
2.5.9.3.3	Test Procedure.....	246
2.5.9.3.3.1	Class Gamma Equipment.....	246
2.5.9.3.3.2	Class Beta Equipment.....	247
2.5.9.3.4	Pass/Fail Criteria.....	247
2.5.9.4	False Alert Rate Test.....	248
2.5.9.4.1	False Alert Rate Simulations for Snapshot Algorithms.....	248
2.5.9.4.2	False Alert Rate Simulations for Non-Snapshot Algorithms.....	249
2.5.9.5	On-Line Verification Test.....	249
2.5.9.5.1	On-Target Computational Test.....	249
2.5.9.5.2	On-Line Behavioral Test.....	250
2.5.10	LNAV/VNAV, LP, LPV Approach Fault Detection.....	250
2.5.10.1	General Test Conditions.....	250
2.5.10.1.1	Test Philosophy.....	250
2.5.10.1.2	GPS Constellation.....	250
2.5.10.1.3	Applicability of RTCA/DO-178B.....	251
2.5.10.1.4	Test Repetition.....	251
2.5.10.1.5	Protection Level/Alert Limit.....	251
2.5.10.1.6	Time-to-Alert.....	251
2.5.10.2	Availability Tests.....	251
2.5.10.3	Off-Line Missed Alert Tests.....	251
2.5.10.3.1	Off-Line Test Setup.....	251
2.5.10.3.2	Selection of Geometries.....	253
2.5.10.3.3	Test Procedures and Pass/Fail Criteria.....	253
2.5.10.4	False Alert Rate Test.....	254
2.5.10.5	On-Line Verification Test.....	254
2.5.10.5.1	On-Target Computational Test.....	254
2.5.10.5.2	On-Line Behavioral Test.....	255
2.5.11	Test Procedures for Class Gamma Equipment.....	255
2.5.11.1	General Gamma Bench Test Procedures.....	255
2.5.11.1.1	Simulated Flight Bench Test Procedures.....	256
2.5.11.1.1.1	Simulated Flight Plan Test 1.....	256
2.5.11.1.1.2	Simulated Flight Plan Test 2.....	257
2.5.11.1.2	Waypoint Distance Display.....	271
2.5.11.1.3	Equipment Response Time Test.....	272
2.5.11.1.4	Loss of Power and Navigation Cautions and Annunciations.....	273
2.5.11.1.5	Cross-Track Deviation Display Bench Test for En Route and Terminal.....	273
2.5.11.1.6	Cross-Track Deviation Display Test for LNAV Approaches.....	277

<b>FAWP</b> .....	<b>279</b>
<b>FAWP</b> .....	<b>281</b>
2.5.11.2 Reserved.....	282
2.5.11.3 Human Factors Bench Tests.....	282
2.5.11.3.1 Equipment Usability .....	282
2.5.11.3.2 Display Brightness and Readability Test .....	282
2.5.11.3.3 Audible Alerts Test.....	285
2.5.11.3.4 Equipment Controls Test .....	286
<b>3.0 INSTALLED EQUIPMENT PERFORMANCE .....</b>	<b>289</b>
<b>4.0 OPERATIONAL CHARACTERISTICS.....</b>	<b>291</b>
<b>5.0 MEMBERSHIP .....</b>	<b>293</b>

**APPENDIX A : SPACE-BASED AUGMENTATION SYSTEM SIGNAL SPECIFICATION..... A-1**

<b>A.1 Introduction.....</b>	<b>A-1</b>
<b>A.2 Signal Characteristics.....</b>	<b>A-1</b>
A.2.1 Carrier Frequency .....	A-1
A.2.2 Spurious Transmissions.....	A-1
A.2.3 Modulation .....	A-1
A.2.4 Carrier Phase Noise .....	A-1
A.2.5 Signal Spectrum.....	A-1
A.2.6 Signal Characteristics Modified Relative To GPS.....	A-2
A.2.6.1 Doppler Shift.....	A-2
A.2.6.2 Carrier Frequency Stability .....	A-2
A.2.6.3 Polarization .....	A-2
A.2.6.4 Code/Carrier Frequency Coherence .....	A-2
A.2.6.5 User Received Signal Levels.....	A-2
A.2.6.6 Correlation Loss .....	A-2
A.2.6.7 Maximum Code Phase Deviation.....	A-3
<b>A.3 SBAS C/A Codes .....</b>	<b>A-3</b>
A.3.1 Requirements .....	A-3
A.3.2 Identification of SBAS Codes .....	A-3
A.3.3 SBAS Codes .....	A-3
A.3.4 Recommended SBAS/GPS Coder Implementation .....	A-4
<b>A.4 SBAS Signal Data Contents and Formats .....</b>	<b>A-5</b>
A.4.1 Introduction .....	A-5
A.4.2 Principles and Assumptions.....	A-6
A.4.2.1 Data Rate.....	A-6
A.4.2.2 Timing.....	A-6
A.4.2.3 Error Corrections .....	A-7
A.4.2.4 Tropospheric Model.....	A-7
A.4.2.5 Residual Tropospheric Error.....	A-9
A.4.2.6 PRN Masks .....	A-9
A.4.2.7 Number of Satellites.....	A-9
A.4.2.8 Issue of Data.....	A-9
A.4.2.9 Acquisition Information .....	A-10
A.4.3 Format Summary .....	A-10

A.4.3.1	Block Format.....	A-10
A.4.3.2	Block Length and Content.....	A-10
A.4.3.3	Parity.....	A-10
A.4.3.4	Preamble .....	A-12
A.4.4	Messages and Relationships Between Message Types .....	A-12
A.4.4.1	Do Not Use for Safety Applications Message Type 0.....	A-14
A.4.4.2	PRN Mask Assignments Message Type 1 .....	A-14
A.4.4.2.1	PRN Mask Transition.....	A-15
A.4.4.3	Fast Corrections Message Types 2 - 5.....	A-15
A.4.4.4	Integrity Information Message Type 6 .....	A-17
A.4.4.5	Fast Correction Degradation Factor Message Type 7 .....	A-18
A.4.4.6	Degradation Factors Message Type 10 .....	A-20
A.4.4.7	Long Term Satellite Error Corrections Message Type 25.....	A-20
A.4.4.8	Mixed Fast Corrections/Long Term Satellite Error Corrections Messages Type 24.....	A-24
A.4.4.9	Ionospheric Grid Point Masks Message Type 18.....	A-25
A.4.4.10	Ionospheric Delay Corrections Messages Type 26 .....	A-31
A.4.4.10.1	Pierce Point Location Determination .....	A-33
A.4.4.10.2	Selection of Ionospheric Grid Points .....	A-34
A.4.4.10.3	Ionospheric Pierce Point Vertical Delay and Model Variance Interpolation .....	A-36
A.4.4.10.4	Computing Slant Ionospheric Delay and Ionospheric Model Variance .....	A-39
A.4.4.11	GEO Navigation Message Type 9 .....	A-40
A.4.4.12	GEO Almanacs Message Type 17 .....	A-41
A.4.4.13	SBAS Service Message Type 27 .....	A-43
A.4.4.13.1	Definition of Regions .....	A-43
A.4.4.14	Null Message Type 63 and Internal Test Message 62 .....	A-46
A.4.4.15	SBAS Network Time/UTC/GLONASS Time Offset Parameters Message Type 12 .....	A-46
A.4.4.16	Clock-Ephemeris Covariance Matrix Message Type 28.....	A-47
A.4.5	Modeling the Degradation of Data .....	A-50
A.4.5.1	Fast and Long-Term Correction Degradation .....	A-51
A.4.5.1.1	Fast Correction Degradation .....	A-51
A.4.5.1.2	Range-Rate Correction Degradation .....	A-52
A.4.5.1.2.1	Range-Rate Correction Degradation - IODF $\neq$ 3 .....	A-52
A.4.5.1.2.2	Range-Rate Correction Degradation - Either IODF = 3 .....	A-52
A.4.5.1.3	Long Term Correction Degradation.....	A-53
A.4.5.1.3.1	Long Term Correction Degradation - Velocity Code =1 .....	A-53
A.4.5.1.3.2	Long Term Correction Degradation - Velocity Code = 0 .....	A-54
A.4.5.1.3.3	GEO Navigation Message Degradation.....	A-54
A.4.5.1.4	Degradation for En Route Through LNAV.....	A-54
A.4.5.2	Degradation of Ionospheric Corrections .....	A-55
A.4.6	Principles and Rules for the Generation and Use of Data.....	A-56
A.4.7	Timing .....	A-56
<b>A.5</b>	<b>References: .....</b>	<b>A-57</b>

**APPENDIX B : STANDARD GPS/WAAS ASSUMPTIONS ..... B-1**

<b>B.1</b>	<b>GPS Constellation.....</b>	<b>B-1</b>
<b>B.2</b>	<b>WAAS Constellation.....</b>	<b>B-1</b>
<b>B.3</b>	<b>Selective Availability .....</b>	<b>B-2</b>
<b>B.4</b>	<b>GPS Satellite Failure .....</b>	<b>B-2</b>
<b>B.5</b>	<b>GPS Constellation for Availability Analysis .....</b>	<b>B-2</b>
<b>B.6</b>	<b>Signal Quality Monitoring .....</b>	<b>B-3</b>
B.6.1	Dead Zones .....	B-3

B.6.2	False Peaks.....	B-3
B.6.3	Distortions.....	B-4
B.6.4	Threat Models.....	B-4
B.6.4.1	Threat Model A.....	B-4
B.6.4.2	Threat Model B.....	B-4
B.6.4.3	Threat Model C.....	B-4

**APPENDIX C : STANDARD RECEIVED SIGNAL AND INTERFERENCE ENVIRONMENT..... C-1**

<b>C.1</b>	<b>Introduction.....</b>	<b>C-1</b>
<b>C.2</b>	<b>Operating Interference Environment.....</b>	<b>C-1</b>
C.2.1	Out-of-Band Interference.....	C-1
C.2.1.1	Out-of-Band Pulse Interference.....	C-2
C.2.2	In-Band and Near-Band Interference.....	C-2
C.2.2.1	In-Band and Near-Band Pulsed Interference.....	C-3
C.2.3	GNSS Noise.....	C-4
<b>C.3</b>	<b>Minimum Standard Antenna Frequency Selectivity.....</b>	<b>C-4</b>

**APPENDIX D : DATA FORMAT FOR HIGH INTEGRITY INFORMATION TO SUPPORT STRAIGHT AND ADVANCED LANDING APPROACH OPERATIONS ... D-1**

<b>D.1</b>	<b>Introduction.....</b>	<b>D-1</b>
<b>D.2</b>	<b>Format.....</b>	<b>D-1</b>
D.2.1	Overall Structure .....	D-1
D.2.2	Data Block Description .....	D-1
D.2.3	Data Block Structure .....	D-2
<b>D.3</b>	<b>Final Approach Segment Data Block.....</b>	<b>D-2</b>
D.3.1	Final Approach Segment Parameter Definition .....	D-3
D.3.2	Final Approach Segment Data Table.....	D-5
<b>D.4</b>	<b>Advanced Procedures Data Blocks .....</b>	<b>D-6</b>
<b>D.5</b>	<b>CRC Definition.....</b>	<b>D-6</b>
<b>D.6</b>	<b>Informative Section .....</b>	<b>D-7</b>
D.6.1	Integrity Protection of Data Blocks .....	D-7
D.6.2	Approach Path Selection .....	D-7
D.6.3	Data Block Generation .....	D-7
D.6.4	Database Formatting and Distribution.....	D-8
D.6.5	CRC Generation and decoding .....	D-8
D.6.6	CRC selection.....	D-9
D.6.7	Reference Coordinate System.....	D-10
<b>D.7</b>	<b>References: .....</b>	<b>D-10</b>

**APPENDIX E : BASELINE WEIGHTED NAVIGATION SOLUTION AND NAVIGATION SYSTEM ERROR ALGORITHMS FOR SBAS VERTICALLY GUIDED APPROACHES ..... E-1**

<b>E.1</b>	<b>Introduction.....</b>	<b>E-1</b>
<b>E.2</b>	<b>Baseline Navigation Solution .....</b>	<b>E-1</b>
<b>E.3</b>	<b>References.....</b>	<b>E-2</b>

<b>APPENDIX F : VELOCITY DATA IN SUPPORT OF ADS-B.....</b>	<b>F-1</b>
<b>F.1 Introduction.....</b>	<b>F-1</b>
<b>F.2 Velocity Solution with Figure of Merit.....</b>	<b>F-1</b>
<b>F.3 References.....</b>	<b>F-4</b>
<b>APPENDIX G : REQUIREMENTS FOR BAROMETREIC ALTIMETER AIDING .....</b>	<b>G-1</b>
<b>G.1 General.....</b>	<b>G-1</b>
<b>G.2 Altimeter Aiding with GNSS Calibration.....</b>	<b>G-1</b>
G.2.1 Requirements for Calibration .....	G-1
G.2.2 Calculation of $\sigma_{\text{baro}}$ .....	G-2
G.2.3 Actual Use of the Altitude Measurement to Augment GNSS .....	G-3
<b>G.3 Barometric Altimeter Aiding Using Baro-corrected Pressure Altitude.....</b>	<b>G-4</b>
G.3.1 Requirements for calibration .....	G-4
G.3.2 Calculation of $\sigma_{\text{baro}}$ .....	G-4
G.3.3 Actual Use of the Barometric Altitude Measurement to Augment GNSS .....	G-5
G.3.4 Requirements for Pilot Interaction.....	G-5
<b>G.4 Test Procedures.....</b>	<b>G-5</b>
<b>G.5 References.....</b>	<b>G-6</b>
<b>APPENDIX H : STANDARD OUTPUT FORMAT .....</b>	<b>H-1</b>
<b>H.1 Introduction.....</b>	<b>H-1</b>
<b>H.2 GPS Minimum Output and Output Timing.....</b>	<b>H-1</b>
H.2.1 Minimum GPS/SBAS Output .....	H-1
H.2.2 Timing .....	H-3
<b>H.3 Other Desirable GPS Outputs .....</b>	<b>H-5</b>
<b>H.4 Summary.....</b>	<b>H-5</b>
<b>H.5 References: .....</b>	<b>H-5</b>
<b>APPENDIX I : MODE SWITCHING FLOWCHART FOR GAMMA EQUIPMENT.....</b>	<b>I-1</b>
<b>I.1 Introduction.....</b>	<b>I-1</b>
<b>APPENDIX J : SBAS-BASED PROTECTION LEVELS FOR EN ROUTE THROUGH LPV APPROACH.....</b>	<b>J-1</b>
<b>J.1 SBAS Protection Level Equations - General Least Squares Solutions.....</b>	<b>J-1</b>
<b>J.2 HPL<sub>SBAS</sub> Parameters .....</b>	<b>J-2</b>
J.2.1 K .....	J-2
J.2.2 Variance of Fast and Long Term Correction Residuals .....	J-3
J.2.3 Variance of Ionospheric Delay .....	J-3
J.2.4 Variance of Airborne Receiver Errors .....	J-4
J.2.5 Variance of Tropospheric Errors .....	J-5
<b>J.3 Rationale for HPL and VPL Parameters .....</b>	<b>J-5</b>
J.3.1 Selection of K Values .....	J-5

J.3.2	Rationale for Fast and Long-Term Residuals.....	J-5
J.3.3	Rationale for Ionospheric Delay Residuals .....	J-6
J.3.4	Rationale for Receiver Residuals .....	J-6
J.3.5	Rationale for Tropospheric Residuals.....	J-6

**APPENDIX K : FAULT DETECTION AND EXCLUSION REFERENCES..... K-1**

**APPENDIX L : THE DIRECT AND INDIRECT GEODETIC PROBLEMS FOR GREAT CIRCLE..... L-1**

L.1	General.....	L-1
L.2	Definitions of Terms .....	L-2
L.3	Nomenclature .....	L-2
L.4	WGS-84 Parameters (from [5]) .....	L-3
L.5	The Indirect Problem .....	L-3
L.6	The Direct Problem .....	L-5
L.7	Validation .....	L-7
L.8	References.....	L-9

**APPENDIX M : TEST CONSIDERATIONS ..... M-1**

M.1	Introduction.....	M-1
M.2	(Initial) Acquisition and Reacquisition Testing Statistical Justification .....	M-1
M.3	Accuracy Statistical Justification .....	M-3
M.4	General Simulator Scenario Conditions.....	M-4
M.5	Example Test Set-up and Compensation of Signals, Noise and Interference .....	M-5
M.5.1	Description of the Test Set-up .....	M-5
M.5.2	Use of the Test Set-up for the Accuracy Test (See 2.5.8).....	M-6

**APPENDIX N : REFERENCE MATERIAL FOR DETERMINING THE MEAN SEA LEVEL HEIGHT FROM WGS-84 COORDINATES..... N-1**

N.1	Introduction.....	N-1
N.1.1	General Altimetry .....	N-1
N.1.2	Mean Sea Level (MSL) Altitude .....	N-2
N.1.3	Barometric Altitude .....	N-2
N.1.4	Radar Altitude .....	N-2
N.1.5	GPS Altitude.....	N-2
N.1.6	SBAS-Derived Altitude .....	N-2

**APPENDIX O : GLOSSARY AND ACRONYMS ..... O-1**

**APPENDIX P : IONOSPHERIC GRID POINT (IGP) SELECTION FLOWCHARTS....P-1**

P.1	Introduction.....	P-1
-----	-------------------	-----

<b>APPENDIX Q : SBAS CONSIDERATIONS FOR HELICOPTERS.....</b>	<b>Q-1</b>
<b>Q.1 General.....</b>	<b>Q-1</b>
Q.1.1 Helicopter/Heliport Deceleration .....	Q-1
Q.1.2 PinS Description.....	Q-1
<b>Q.2 PinS Approach Operations .....</b>	<b>Q-1</b>
Q.2.1 Fictitious Helipoint Equivalence to Fictitious Threshold Point .....	Q-1
Q.2.2 FAS Data Block Application to PinS Procedures.....	Q-1
Q.2.3 PinS Lateral Display Scaling .....	Q-3
Q.2.4 Vertical Display Scaling.....	Q-3
<b>Q.3 Deceleration Point Annunciation .....</b>	<b>Q-3</b>
<b>Q.4 Selective CDI and HAL Values to Support Tighter Route Area Semi-widths .....</b>	<b>Q-4</b>
<b>Q.5 Autopilot Considerations .....</b>	<b>Q-4</b>
<b>Q.6 Heliport Approach Database Considerations .....</b>	<b>Q-4</b>

<b>APPENDIX R : REQUIREMENTS AND TEST PROCEDURES FOR TIGHTLY INTEGRATED GPS/INERTIAL SYSTEMS .....</b>	<b>R-1</b>
<b>R.1 Introduction.....</b>	<b>R-1</b>
<b>R.2 Requirements .....</b>	<b>R-1</b>
R.2.1 General FDE Requirements .....	R-1
R.2.1.1 Fault Free Performance .....	R-2
R.2.2 Unique Additional Requirements.....	R-3
R.2.2.1 Assumed Failure Mechanisms.....	R-3
R.2.2.2 Detection limit.....	R-4
R.2.2.3 SatZap .....	R-5
R.2.2.4 Receiver Clock Aiding .....	R-5
R.2.2.5 Altitude Aiding.....	R-5
R.2.2.6 Discriminator Averaging.....	R-6
R.2.2.7 Inertial Coasting Performance Evaluation.....	R-6
R.2.2.7.1 Accuracy Coasting .....	R-6
R.2.2.7.2 Integrity Coasting .....	R-7
R.2.2.8 Gravity Compensation.....	R-8
<b>R.3 Tightly Integrated GPS/Inertial Design Concepts.....</b>	<b>R-9</b>
R.3.1 Integration Methods .....	R-9
R.3.1.1 Pre-residual (Innovation) Screening.....	R-10
R.3.1.2 Post-Residual Monitoring .....	R-10
R.3.1.3 Additional Measurement Bias States.....	R-10
R.3.1.4 Multiple Kalman Filters .....	R-10
R.3.1.5 Extrapolation Method .....	R-10
R.3.1.6 Solution Separation Method.....	R-11
R.3.2 Detection and Exclusion Mechanisms .....	R-11
R.3.2.1 Transient Detection/Exclusion for 2 nmi/hour Grade Systems .....	R-11
R.3.2.2 Satellite Redundancy.....	R-11
R.3.2.3 Integrity Coasting.....	R-11
R.3.2.4 Gravity/Schuler Coupling.....	R-11
R.3.2.5 Other Schuler Coupling Related Effects .....	R-12
<b>R.4 Assumptions .....</b>	<b>R-12</b>
R.4.1 Signal Error Model .....	R-12
R.4.2 Satellite Clock Drift Characteristics.....	R-13

<b>R.5</b>	<b>Validation .....</b>	<b>R-13</b>
R.5.1	Categorization of Detection and Exclusion Mechanisms .....	R-13
R.5.1.1	Examples .....	R-14
R.5.2	Covariance Simulation .....	R-14
R.5.2.1	Covariance Simulation Methods for Availability Evaluation .....	R-14
R.5.3	False Alert Probability .....	R-15
R.5.4	Fault Free Accuracy Performance .....	R-16
R.5.5	Off-Line Rare Normal Verification .....	R-16
R.5.6	Off-Line Detection/Exclusion Verification .....	R-16
R.5.6.1	Detection and Exclusion Mechanism Equivalent to RAIM .....	R-17
R.5.6.2	Claimed Additional Detection and Exclusion Mechanisms .....	R-17
R.5.6.2.1	Examples .....	R-17
R.5.6.2.1.1	RAIM with Transient Detection/Exclusion .....	R-17
R.5.6.2.1.2	Solution Separation Detection and Exclusion .....	R-18
R.5.6.2.2	Reference RAIM Models .....	R-18
R.5.6.3	Integrity Coasting .....	R-19
R.5.7	On-Line Validation .....	R-19
R.5.8	Gravity Compensation Validation .....	R-19
R.5.9	Ionospheric Error Models .....	R-21
R.5.9.1	Ionospheric Daily Variation .....	R-21
R.5.9.2	Ionospheric Storms .....	R-21
<b>R.6</b>	<b>References .....</b>	<b>R-21</b>
<b>APPENDIX S</b>	<b>: PROCESSING FLOW DIAGRAMS .....</b>	<b>S-1</b>
S.1	Introduction .....	S-1
<b>APPENDIX T</b>	<b>: GEO BIAS ANALYSIS TOOL .....</b>	<b>T-1</b>
T.1	GEO Bias Algorithm Rationale .....	T-1
T.2	GEO Bias Algorithm Procedure (Overview) .....	T-1
T.3	Analysis .....	T-2
T.3.1	GEO Filter Models .....	T-3
T.3.1.1	Future GEOs .....	T-5
T.3.2	Range Normalization .....	T-5
T.4	Bias Model Tool: Instructions and examples .....	T-6
<b>APPENDIX U</b>	<b>: GUIDANCE MATERIAL FOR INTERFACING WITH ADS-B .....</b>	<b>U-1</b>
U.1	Purpose and Scope .....	U-1
U.2	Position Output and Validity .....	U-1
U.3	Horizontal Figure of Merit (HFOM) .....	U-1
U.4	Horizontal Protection Limit (HPL) .....	U-1
U.5	Velocity .....	U-2
U.6	Vertical Figure of Merit and Vertical Protection Limit (VPL) .....	U-2
<b>APPENDIX V</b>	<b>: CHANGE 1 FOR DO-229D .....</b>	<b>V-1</b>

## TABLE OF FIGURES

FIGURE 1-1 WAAS ARCHITECTURE.....	5
FIGURE 1-2 FUNCTIONAL CLASSES .....	10
FIGURE 1-3 DIAGRAM OF FDE CONDITIONS .....	16
FIGURE 1-4 MARKOV CHAIN FOR FDE .....	17
FIGURE 1-5 EXAMPLE FDE EVENTS .....	18
FIGURE 2-1 SENSITIVITY AND DYNAMIC RANGE CONFIGURATION.....	40
FIGURE 2-2A RECEIVER BANDWIDTH AND AVERAGE CORRELATOR SPACING FOR E-L DISCRIMINATOR TRACKING OF GPS SATELLITES.....	57
FIGURE 2-2B RECEIVER BANDWIDTH AND AVERAGE CORRELATOR SPACING FOR DD DISCRIMINATOR TRACKING OF GPS SATELLITES.....	57
FIGURE 2-3 TF LEG .....	81
FIGURE 2-4 RF LEG .....	82
FIGURE 2-5 DIRECT-TO PATH DEFINITION .....	83
FIGURE 2-6 CF LEG .....	83
FIGURE 2-7 FLY-BY THEORETICAL TRANSITION AREA .....	85
FIGURE 2-8 FLY-OVER THEORETICAL TRANSITION AREA .....	86
FIGURE 2-9 WAYPOINT SEQUENCING .....	87
FIGURE 2-10 DEFAULT NAVIGATION MODES.....	97
FIGURE 2-11 FULL-SCALE DEFLECTION AND DEFINED PATH FOR NORMAL LNAV APPROACH (not VTF approach).....	104
FIGURE 2-12 FULL SCALE DEFLECTION AND DEFINED PATH FOR LNAV VTF APPROACH .....	105
FIGURE 2-13 MISSED APPROACH SCENARIOS .....	106
FIGURE 2-14 FINAL APPROACH SEGMENT DEFINITION.....	113
FIGURE 2-15 VTF FINAL APPROACH SEGMENT LATERAL DEVIATIONS WITH FAS DATA BLOCK.....	115
FIGURE 2-16 FINAL APPROACH SEGMENT VERTICAL DEVIATIONS .....	118
FIGURE 2-17 FLIGHT PROFILE FOR FLIGHT PLAN 1 .....	270
FIGURE 2-18 FLIGHT PROFILE FOR FLIGHT PLAN 2 .....	271
FIGURE 2-19 CROSS-TRACK DEVIATION FOR EN ROUTE AND TERMINAL .....	275
FIGURE 2-20 CROSS TRACK DEVIATION FOR VTF LNAV APPROACH .....	279
FIGURE 2-21 CROSS-TRACK DEVIATION FOR LNAV APPROACH.....	281
FIGURE A-1 SBAS/GPS CODER IMPLEMENTED WITH SINGLE G2 OUTPUT PLUS PROGRAMMABLE G2 DELAY .....	A-5
FIGURE A-2 SBAS/GPS CODER IMPLEMENTED WITH A PROGRAMMABLE INITIAL G2 STATE.....	A-5
FIGURE A-3 CONVOLUTIONAL ENCODING .....	A-7
FIGURE A-4 DATA BLOCK FORMAT.....	A-10
FIGURE A-5 INTERRELATIONSHIPS OF MESSAGES .....	A-13
FIGURE A-6 EXAMPLE PRN MASK.....	A-15
FIGURE A-7 TYPES 2 - 5 FAST CORRECTIONS MESSAGES FORMAT.....	A-16
FIGURE A-8 TYPE 6 INTEGRITY MESSAGE FORMAT.....	A-18
FIGURE A-9 TYPE 7 FAST CORRECTION DEGRADATION FACTOR MESSAGE FORMAT ...	A-19
FIGURE A-10 TYPE 25 LONG TERM SATELLITE ERROR CORRECTIONS Velocity Code = 0	A-21
FIGURE A-11 TYPE 25 LONG TERM SATELLITE ERROR CORRECTIONS Velocity Code = 1	A-23
FIGURE A-12 TYPE 24 MIXED FAST CORRECTION/LONG TERM SATELLITE ERROR CORRECTIONS MESSAGE FORMAT.....	A-25
FIGURE A-13 EXAMPLE OF AN IONOSPHERIC GRID MASK.....	A-27
FIGURE A-14 PREDEFINED GLOBAL IGP GRID (BANDS 9 AND 10 ARE NOT SHOWN) .....	A-30
FIGURE A-15 TYPE 18 IGP MASK MESSAGE FORMAT.....	A-31

FIGURE A-16	TYPE 26 IONOSPHERIC DELAY CORRECTIONS MESSAGE FORMAT .....	A-32
FIGURE A-17	IONOSPHERIC PIERCE POINT GEOMETRY .....	A-34
FIGURE A-18	IONOSPHERIC GRID POINT INTERPOLATION .....	A-36
FIGURE A-19	FOUR-POINT INTERPOLATION ALGORITHM DEFINITIONS .....	A-38
FIGURE A-20	THREE-POINT INTERPOLATION ALGORITHM DEFINITIONS .....	A-39
FIGURE A-21	TYPE 9 GEO NAVIGATION MESSAGE FORMAT .....	A-40
FIGURE A-22	TYPE 17 GEO ALMANACS MESSAGE FORMAT .....	A-42
FIGURE A-23	SERVICE MESSAGE TYPE 27 .....	A-44
FIGURE A-24	TYPE 28 CLOCK-EPHEMERIS COVARIANCE MATRIX MESSAGE FORMAT .....	A-49
FIGURE C-1	INTERFERENCE LEVELS AT THE ANTENNA PORT .....	C-1
FIGURE C-2	IN-BAND AND NEAR-BAND INTERFERENCE ENVIRONMENTS .....	C-2
FIGURE C-3	FREQUENCY SELECTIVITY .....	C-5
FIGURE D-1	FINAL APPROACH SEGMENT DIAGRAM .....	D-2
FIGURE D-2	PROBABILITY OF UNDETECTED ERROR .....	D-9
FIGURE D-3	PROBABILITIES OF CORRECT DECODING AND DETECTED ERRORS .....	D-10
FIGURE H-1	GPS TIMING RELATIONSHIPS .....	H-4
FIGURE M-1	(RE)ACQUISITION TEST PROBABILITY STATISTICS .....	M-2
FIGURE M-2	PSEUDORANGE ACCURACY TEST PASS CRITERIA .....	M-3
FIGURE M-3	PSEUDORANGE ACCURACY TEST PASS PROBABILITY .....	M-4
FIGURE P-1	GRID POINT SELECTION CRITERIA .....	P-2
FIGURE P-2	ABS IPP LATTITUDE BELOW 60 DEG (5X5) .....	P-3
FIGURE P-3	ABS IPP LATITUDE BELOW 85 DEG .....	P-4
FIGURE P-4	ABS IPPLATITUDE BETWEEN 60 & 75 DEG BANDS 9-10 .....	P-5
FIGURE P-6	ABS IPP LATITUDE ABOVE 85 DEG .....	P-6
FIGURE P-7	ABS IPP LATITUDE BELOW 60 DEG (10X10 SQUARES) .....	P-7
FIGURE P-8	ABS IPP LATITUDE BELOW 60 DEG (10X10 TRIANGLES) .....	P-8
FIGURE P-9	ABS IPP LATITUDE BETWEEN 60 & 75 DEG BANDS 9-10 .....	P-9
FIGURE Q-1	LATERAL DISPLAY SCALING FOR PinS APPROACH OPERATIONS .....	Q-3
FIGURE R-1	FLIGHT PROFILE ASSUMED FOR THE COASTING TIMES .....	R-8
FIGURE S-1	APPLICATION OF SBAS CORRECTION PARAMETERS .....	S-2
FIGURE S-2	SATELLITE CORRECTIONS (WHEN SBAS-BASED SIGMA VALUES ARE APPLIED) .....	S-3
FIGURE S-3	IONOSPHERIC CORRECTIONS .....	S-4
FIGURE S-4	GEOMETRIC RANGE (WHEN SBAS-BASED SIGMA VALUES ARE APPLIED) .....	S-5
FIGURE S-5	POSITION SOLUTION (WHEN SBAS-BASED SIGMA VALUES ARE APPLIED) .....	S-6
FIGURE S-6	CLOCK/EPHEMERIS CONTRIBUTION TO WEIGHT USED FOR HPLFD FOR EN ROUTE THROUGH APPROACH (LNAV) .....	S-7
FIGURE T-1	COMPARISON OF CORRELATION PEAKS FOR A NARROWBAND GEO AND A GPS CORRELATION PEAK .....	T-1
FIGURE T-2	OVERVIEW OF GEO BIAS CALCULATION ALGORITHM FOR A SINGLE RECEIVER .....	T-2
FIGURES T-3 AND T-4	MAGNITUDE AND GROUP DELAY RESPONSES OF THE WAAS GEO SIGNAL GENERATOR IN COMBINATION WITH THE NARROWBAND GEO (AOR-W) .....	T-4
FIGURES T-5 AND T-6	MAGNITUDE AND GROUP DELAY RESPONSES OF THE GCCS GEO SIGNAL GENERATOR IN COMBINATION WITH THE WIDEBAND (PANAMSAT/ORBITAL) GEO .....	T-4
FIGURES T-7 AND T-8	MAGNITUDE AND PHASE RESPONSES OF A SAMPLE RECEIVER (FINAL IF, PRECORRELATION) FILTER .....	T-4
FIGURES T-9 AND T-10	ALL EARLY-MINUS-LATE AND DOUBLE-DELTA TRACKING ERRORS OF GPS AND INMARSAT NARROWBAND GEO SIGNALS AS OUTPUT BY TOOL GIVEN THE SAMPLE INPUT PARAMETERS ABOVE (EXAMPLE 1) .....	T-8

FIGURES T-11 AND T-12 ALL EARLY-MINUS-LATE AND DOUBLE-DELTA TRACKING ERRORS OF GPS AND MTSAT NARROWBAND GEO SIGNALS AS OUTPUT BY TOOL GIVEN THE SAMPLE INPUT PARAMETERS ABOVE (EXAMPLE 1) .....	T-8
FIGURES T-13 AND T-14 ALL EARLY-MINUS-LATE AND DOUBLE-DELTA TRACKING ERRORS OF GPS AND WIDEBAND GEO SIGNALS AS OUTPUT BY TOOL GIVEN THE SAMPLE INPUT PARAMETERS ABOVE (EXAMPLE 1) .....	T-9
FIGURES T-15 AND T-16 SUMMARY OF GEO BIAS ERRORS FOR ALL (32+19) GPS AND SBAS PRNS AS OUTPUT BY TOOL GIVEN THE SAMPLE INPUT PARAMETERS ABOVE (EXAMPLE 1). RECEIVER DESIGN PASSES IF ALL BIASES ARE BELOW LIMTS INDICATED ON PLOTS .....	T-9
FIGURES T-17 AND T-18 ALL EARLY-MINUS-LATE AND DOUBLE-DELTA TRACKING ERRORS OF GPS AND INMARSAT NARROWBAND GEO SIGNALS AS OUTPUT BY TOOL GIVEN THE SAMPLE INPUT PARAMETERS ABOVE (EXAMPLE 2) .....	T-11
FIGURES T-19 AND T-20 ALL EARLY-MINUS-LATE AND DOUBLE-DELTA TRACKING ERRORS OF GPS AND MTSAT NARROWBAND GEO SIGNALS AS OUTPUT BY TOOL GIVEN THE SAMPLE INPUT PARAMETERS ABOVE (EXAMPLE 2) .....	T-11
FIGURES T-21 AND T-22 ALL EARLY-MINUS-LATE AND DOUBLE-DELTA TRACKING ERRORS OF GPS AND WIDEBAND GEO SIGNALS AS OUTPUT BY TOOL GIVEN THE SAMPLE INPUT PARAMETERS ABOVE (EXAMPLE 2) .....	T-12
FIGURES T-23 AND T-24 SUMMARY OF GEO BIAS ERRORS FOR ALL (32+19) GPS AND SBAS PRNS AS OUTPUT BY TOOL GIVEN THE SAMPLE INPUT PARAMETERS ABOVE (EXAMPLE 2). RECEIVER DESIGN PASSES IF ALL BIASES ARE BELOW LIMTS INDICATED ON PLOTS .....	T-12

## TABLE OF TABLES

TABLE 1-1 EQUIPMENT CLASSES AND REQUIREMENTS ORGANIZATION.....	11
TABLE 2-1 TIMEOUT INTERVALS .....	31
TABLE 2-2 FAST CORRECTION USER TIME-OUT INTERVAL EVALUATION .....	32
TABLE 2-3 URA VALUES .....	44
TABLE 2-4A GPS TRACKING CONSTRAINTS FOR E-L DLL DISCRIMINATORS .....	55
TABLE 2-4B GPS TRACKING CONSTRAINTS FOR DD DLL DISCRIMINATORS .....	56
TABLE 2-4C SBAS RANGING FUNCTION TRACKING CONSTRAINTS .....	58
TABLE 2-5 SAFETY-CRITICAL FUNCTIONS .....	69
TABLE 2-6 LABELS AND MESSAGES .....	75
TABLE 2-7 FLY-BY THEORETICAL TRANSITION AREA 'R' AND Y VALUES .....	84
TABLE 2-8 NON-NUMERIC ELECTRICAL OUTPUT REQUIREMENTS .....	91
TABLE 2-9 NON-NUMERIC DISPLAY REQUIREMENTS.....	91
TABLE 2-10 NON-NUMERIC DISPLAY REQUIREMENTS.....	96
TABLE 2-11 DEFINITION OF DEFAULT NAVIGATION MODES.....	98
TABLE 2-12 SUMMARY OF TYPICAL MODE SWITCHING TRANSITIONS.....	98
TABLE 2-13 SUMMARY OF CHANGES IN CROSS-TRACK FULL SCALE DEFLECTION FOR MODE SWITCHING .....	99
TABLE 2-14 CLASS BETA-1 ENVIRONMENTAL TEST REQUIREMENTS .....	139
TABLE 2-15 CLASS GAMMA-1 ENVIRONMENTAL TEST REQUIREMENTS .....	140
TABLE 2-16 CLASS BETA-2 ENVIRONMENTAL TEST REQUIREMENTS .....	141
TABLE 2-17 CLASS GAMMA-2 ENVIRONMENTAL TEST REQUIREMENTS .....	142
TABLE 2-18 CLASS BETA-3 ENVIRONMENTAL TEST REQUIREMENTS .....	143
TABLE 2-19 CLASS GAMMA-3 ENVIRONMENTAL TEST REQUIREMENTS .....	144
TABLE 2-20 CLASS DELTA-4 ENVIRONMENTAL TEST REQUIREMENTS.....	145
TABLE 2-21 TEST CROSS REFERENCE MATRIX.....	151

TABLE 2-22 GRADUATED SAMPLING PASS/FAIL CRITERIA.....	231
TABLE 2-23 STEADY STATE ACCURACY TEST CWI VALUES* .....	237
TABLE 2-24 SATELLITE EQUIVALENT POWER SPECTRAL DENSITY .....	237
TABLE 2-25 PASS THRESHOLD TABLE .....	239
TABLE 2-26 MAXIMUM NUMBER OF OUTCOMES TO OFF-LINE FDE TEST.....	248
TABLE 2-27 WAYPOINT INFORMATION FOR FIRST FLIGHT PLAN FOR SIMULATED FLIGHT PLAN TEST 1 .....	256
TABLE 2-28 WAYPOINT INFORMATION FOR SIMULATED FLIGHT PLAN TEST 2 .....	258
TABLE 2-29 SIMULATED FLIGHT PLAN TEST NUMBER 1 .....	259
TABLE 2-30 SIMULATED FLIGHT PLAN TEST NUMBER 2 .....	265
TABLE 2-31 WAYPOINTS FOR CROSS TRACK DEVIATION BENCH TEST FOR EN ROUTE AND TERMINAL .....	276
TABLE 2-32 TEST SEQUENCE FOR EN ROUTE AND TERMINAL CROSS-TRACK DEVIATION .....	277
TABLE 2-33 TEST SEQUENCE FOR VTF LNAV APPROACH CROSS TRACK DEVIATION ....	278
TABLE 2-34 TEST SEQUENCE FOR LNAV APPROACH CROSS-TRACK DEVIATION.....	280
TABLE 2-35 HUMAN FACTORS TEST: CHECKLIST 1. EQUIPMENT USABILITY .....	283
TABLE 2-36 HUMAN FACTORS TEST: CHECKLIST 2. DISPLAY BRIGHTNESS .....	284
TABLE 2-37 HUMAN FACTORS TEST: CHECKLIST 3. AUDIBLE ALERTS .....	286
TABLE 2-38 HUMAN FACTORS TEST: CHECKLIST 4. EQUIPMENT CONTROLS.....	287
TABLE A-1 SBAS RANGING C/A CODES.....	A-4
TABLE A-2 METEOROLOGICAL PARAMETERS FOR TROPOSPHERIC DELAY .....	A-8
TABLE A-3 MESSAGE TYPES.....	A-13
TABLE A-4 PRN MASK ASSIGNMENTS .....	A-14
TABLE A-5 TYPE 6 INTEGRITY MESSAGE CONTENT .....	A-18
TABLE A-6 EVALUATION OF UDRE <sub>i</sub> .....	A-18
TABLE A-7 TYPE 7 FAST CORRECTION DEGRADATION FACTOR MESSAGE CONTENTS ... .....	A-19
TABLE A-8 FAST CORRECTIONS DEGRADATION FACTOR AND USER TIME-OUT INTERVAL EVALUATION.....	A-19
TABLE A-9 TYPE 10 DEGRADATION factors.....	A-20
TABLE A-10 TYPE 25 LONG TERM SATELLITE ERROR CORRECTIONS HALF MESSAGE PARAMETERS WITH VELOCITY CODE OF 0.....	A-22
TABLE A-11 TYPE 25 LONG TERM SATELLITE ERROR CORRECTIONS HALF MESSAGE PARAMETERS WITH VELOCITY CODE OF 1 .....	A-23
TABLE A-12 PREDEFINED WORLD-WIDE IGP SPACING – Bands 0 - 8 .....	A-25
TABLE A-13 PREDEFINED WORLD-WIDE IGP SPACING - BANDS 9 - 10.....	A-25
TABLE A-14 IONOSPHERIC MASK BANDS .....	A-28
TABLE A-14 IONOSPHERIC MASK BANDS (CONTINUED) .....	A-29
TABLE A-15 TYPE 18 IGP MASK MESSAGE CONTENTS .....	A-31
TABLE A-16 IONOSPHERIC DELAY MODEL PARAMETERS FOR MESSAGE TYPE 26.....	A-32
TABLE A-17 EVALUATION OF GIVE <sub>i</sub> .....	A-33
TABLE A-18 TYPE 9 GEO NAVIGATION MESSAGE PARAMETERS .....	A-41
TABLE A-19 TYPE 17 GEO ALMANACS MESSAGE PARAMETERS .....	A-42
TABLE A-20 TYPE 27 SERVICE MESSAGE PARAMETERS .....	A-45
TABLE A-21 $\delta$ UDRE INDICATOR EVALUATION .....	A-46
TABLE A-22 SBAS NETWORK TIME/UTC PARAMETERS .....	A-47
TABLE A-23 UTC STANDARD IDENTIFIER .....	A-47
TABLE A-24 TYPE 28 CLOCK-EPHEMERIS COVARIANCE MATRIX MESSAGE PARAMETERS .....	A-50
TABLE A-25 MESSAGE CONTENT BROADCAST INTERVALS .....	A-57
TABLE B-1 OPTIMIZED 24 GPS CONSTELLATION .....	B-1

TABLE B-2	GPS CONSTELLATION ON DECEMBER 1, 1995 AT 00:00 UTC.....	B-3
TABLE C-1	OUT-OF-BAND PULSE INTERFERENCE .....	C-2
TABLE C-2	IN-BAND AND NEAR-BAND INTERFERENCE BANDWIDTH DEFINITIONS.....	C-3
TABLE C-3	IN-BAND AND NEAR-BAND PULSE INTERFERENCE .....	C-4
TABLE C-4	EFFECTIVE NOISE DENSITY FOR ALL GNSS SOURCES .....	C-4
TABLE C-5	FREQUENCY SELECTIVITY .....	C-5
TABLE D-1	FINAL APPROACH SEGMENT (FAS).....	D-5
TABLE G-1	PRESSURE GRADIENT ERRORS (KNOWN GL).....	G-3
TABLE G-2	PRESSURE GRADIENT ERRORS (UNKNOWN GL).....	G-3
TABLE H-1	MINIMUM GPS OUTPUT .....	H-2
TABLE L-1	TEST CASE INPUT .....	L-7
TABLE L-2	TEST CASE OUTPUT .....	L-8
TABLE L-3	NUMBER OF ITERATIONS .....	L-8
TABLE M-1	GRADUATED SAMPLING PASS/FAIL CRITERIA.....	M-2
TABLE R-1	SUMMARY OF FDE REQUIREMENTS.....	R-1
TABLE R-2	SUMMARY OF FAILURE TYPE PROBABILITIES .....	R-4
TABLE R-3	ACCURACY COASTING PERFORMANCE EXAMPLE .....	R-7
TABLE R-4	INTEGRITY COASTING PERFORMANCE EXAMPLE .....	R-8
TABLE R-5	EQUIVALENT ALTITUDE ACCURACY .....	R-12
TABLE R-6	REQUIRED NUMBER OF TRIALS FOR EACH FAILURE MODE.....	R-17

---

## 1.0 PURPOSE AND SCOPE

### 1.1 Introduction

This document contains minimum operational performance standards (MOPS) for airborne navigation equipment (2D and 3D) using the Global Positioning System (GPS) augmented by Satellite-Based Augmentation Systems (SBAS); which, in the U.S. is the Wide Area Augmentation System (WAAS). DO-229 only provides standards for single frequency airborne navigation equipment. A separate document will be created in the future to address standards for dual frequency equipment. These standards are intended to be applicable to other SBAS providers, such as European Geostationary Navigation Overlay Service (EGNOS) and Japan's Multi-functional Transport Satellite (MTSAT) Satellite-based Augmentation System (MSAS).

In this document, the term “shall” is used to indicate requirements. An approved design should comply with every requirement, which can be assured by inspection, test, analysis, or demonstration. The term “must” is used to identify items that are important but are either duplicated somewhere else in the document as a “shall”, or are considered to be outside the scope of this document. The term “should” is used to denote a recommendation that would improve the SBAS equipment, but does not constitute a requirement.

The standards define minimum performance, functions and features for SBAS-based sensors that provide position information to a multi-sensor system or separate navigation system. They also address SBAS-based Area Navigation (RNAV) equipment to be used for the en route, terminal, and Lateral Navigation (LNAV) phases of flight. These standards are based upon a nominal allocation of the aircraft-level requirements in RTCA/DO-236B, *Minimum Aviation System Performance Standards: Required Navigation Performance for Area Navigation*, accounting for the unique issues associated with SBAS and GNSS navigation service and minimizing the need for pilot training. These standards also define performance, functions and features for equipment that satisfies the requirements for Lateral Navigation/Vertical Navigation (LNAV/VNAV), Localizer Performance without vertical guidance (LP), and Localizer Performance with Vertical guidance (LPV) instrument procedures. The standards cover SBAS-based equipment that is designed to serve combinations of the above phases of flight.

Compliance with these standards by manufacturers, installers and users is recommended as one means of assuring that the equipment will satisfactorily perform its intended functions under conditions encountered in routine aeronautical operations, and will ensure a basic compatibility with the requirements defined in RTCA/DO-236B. Manufacturers and operators who elect to comply directly with the requirements of RTCA/DO-236B as part of an aircraft certification (type certificate or supplemental type certificate) may bypass these RNAV standards, but are not expected to be eligible for a Class Gamma TSO authorization.

The regulatory application of these standards is the responsibility of appropriate government agencies. In the United States, the Federal Aviation Administration (FAA) has published a Technical Standard Order (TSO) for GPS/WAAS equipment to reference the requirements and bench test procedures in Section 2.

The word “equipment”, as used in this document, includes all components or units necessary (as determined by the equipment manufacturer or installer) to properly perform its intended function. For example, the airborne “equipment” may include: sensor(s), a computer unit, an input-output unit that interfaces with existing aircraft