

INTERNATIONAL STANDARD

NORME INTERNATIONALE



Medical electrical equipment –

Part 2-78: Particular requirements for basic safety and essential performance of medical robots for rehabilitation, assessment, compensation or alleviation

Appareils électromédicaux –

Partie 2-78: Exigences particulières pour la sécurité de base et les performances essentielles des robots médicaux associés à la rééducation, l'évaluation, la compensation ou l'atténuation



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INTERNATIONAL ELECTROTECHNICAL COMMISSION

MEDICAL ELECTRICAL EQUIPMENT –**Part 2-78: Particular requirements for basic safety and essential performance of medical robots for rehabilitation, assessment, compensation or alleviation**

FOREWORD

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This consolidated version of the official IEC Standard and its amendment has been prepared for user convenience.

IEC 80601-2-78 edition 1.1 contains the first edition (2019-07) [documents 62D/1676/FDIS and 62D/1688/RVD] and its amendment 1 (2024-03) [documents 62D/2085A/FDIS and 62D/2109/RVD].

In this Redline version, a vertical line in the margin shows where the technical content is modified by amendment 1. Additions are in green text, deletions are in strikethrough red text. A separate Final version with all changes accepted is available in this publication.

International standard IEC 80601-2-78 has been prepared by IEC subcommittee 62D: Electromedical equipment, of IEC Technical Committee 62: Electrical equipment in medical practice, and ISO Technical Committee 299: Robotics.

This publication is published as a double logo standard.

This document has been drafted in accordance with the ISO/IEC Directives, Part 2.

In this document, the following print types are used:

- requirements and definitions: roman type;
- *test specifications: italic type;*
- informative material appearing outside of tables, such as notes, examples and references in smaller type. Normative text of tables is also in a smaller type;
- TERMS DEFINED IN CLAUSE 3 OF THE GENERAL STANDARD, IN THIS PARTICULAR STANDARD OR AS NOTED: SMALL CAPITALS.

In referring to the structure of this document, the term

- "clause" means one of the seventeen numbered divisions within the table of contents, inclusive of all subdivisions (e.g. Clause 7 includes subclauses 7.1–7.2 etc.);
- "subclause" means a numbered subdivision of a clause (e.g. 7.1.1, 7.2 and 7.2.1 are all subclauses of Clause 7).

References to clauses within this document are preceded by the term "Clause" followed by the clause number. References to subclauses within this particular standard are by number only.

In this document, the conjunctive "or" is used as an "inclusive or" so a statement is true if any combination of the conditions is true.

The verbal forms used in this document conform to usage described in Clause 7 of the ISO/IEC Directives, Part 2. For the purposes of this document, the auxiliary verb:

- "shall" means that compliance with a requirement or a test is mandatory for compliance with this document;
- "should" means that compliance with a requirement or a test is recommended but is not mandatory for compliance with this document;
- "may" is used to describe a permissible way to achieve compliance with a requirement or test.

An asterisk (*) as the first character of a title or at the beginning of a paragraph or table title indicates that there is guidance or rationale related to that item in Annex AA.

A list of all parts of the IEC 80601 and IEC 60601 International Standard, published under the general title *Medical electrical equipment*, can be found on the IEC website.

The committee has decided that the contents of this document and its amendment will remain unchanged until the stability date indicated on the IEC website under webstore.iec.ch in the data related to the specific document. At this date, the document will be

- reconfirmed,
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INTRODUCTION

This part of IEC 80601 International Standard was written at a time when technical evolution of MEDICAL ROBOTS was in rapid progress and the scientific foundation of safe use was still being expanded.

This document is the result of work that began in ISO/TC 184/SC 2/WG 7 in October 2006 on personal care ROBOTS, to address an emerging type of MEDICAL ROBOT that was used outside of an industrial environment. That group was working on a new standard, ISO 13482, which was published as an International Standard (IS) in 2014. While initially focused on non-medical applications, WG 7 recognized that work was needed on medical devices utilizing robotic technology. In October 2009, ISO/TC 184/SC 2 established a WG 7, *Study Group (SG) on Medical care robots*, comprised of experts from Canada, France, Germany, Japan, Korea, Romania, Switzerland, UK and USA.

The work of ISO/TC 184/SC 2/WG 7 SG cumulated in a proposal to form a Joint Working Group (JWG 9) with IEC/TC 62/SC 62A focusing on MEDICAL ELECTRICAL EQUIPMENT using robotic technology. This JWG began developing a technical report (IEC TR 60601-4-1) dealing with degree of autonomy. While developing this document, a particular standard was deemed required for REHABILITATION type ROBOTS. This led to the creation of a Joint Working Group 36 (MEDICAL ROBOTS for REHABILITATION) in April, 2015 within IEC/TC 62/SC 62D to develop particular requirements of SAFETY of MEDICAL ELECTRICAL EQUIPMENT and MEDICAL ELECTRICAL SYSTEMS for REHABILITATION type ROBOTS. ISO/TC 184/SC 2 has since been promoted to ISO/TC 299, and JWG 9 has merged with JWG 35 and 36 to form JWG 5 (MEDICAL ROBOT Safety) on the ISO side. This proposal was approved from both IEC and ISO and work began.

The minimum safety requirements specified in this particular standard are presented to provide for an acceptable degree of BASIC SAFETY and ESSENTIAL PERFORMANCE for MEDICAL ROBOTS that physically interact with a PATIENT WITH AN IMPAIRMENT, to support or perform REHABILITATION, ASSESSMENT, COMPENSATION or ALLEVIATION related to the PATIENT'S MOVEMENT FUNCTIONS.

The requirements are followed by particular specifications for the relevant tests.

INTRODUCTION to Amendment 1

At the October 2019 meeting of IEC SC 62D in Shanghai, China, the subcommittee discussed the need for administrative/technical changes to most 62D standards after completion of the amendment projects within the IEC 60601-1 series. Those projects were all completed and the amendments published in 2020.

The full list of IEC SC 62D documents that will be amended or revised can be found within the IEC document 62D/1792/DC. The results and comments on the DC can be found within 62D/1800/INF. The review report for this amendment is 62D/1882/RR.

MEDICAL ELECTRICAL EQUIPMENT –

Part 2-78: Particular requirements for basic safety and essential performance of medical robots for rehabilitation, assessment, compensation or alleviation

201.1 Scope, object and related standards

Clause 1 of the general standard¹ applies, except as follows:

201.1.1 Scope

Replacement:

This part of IEC 80601 applies to the general requirements for BASIC SAFETY and ESSENTIAL PERFORMANCE of MEDICAL ROBOTS that physically interact with a PATIENT with an IMPAIRMENT to support or perform REHABILITATION, ASSESSMENT, COMPENSATION or ALLEVIATION related to the PATIENT'S MOVEMENT FUNCTIONS, as intended by the MANUFACTURER.

If a clause or subclause is specifically intended to be applicable to ME EQUIPMENT only, or to ME SYSTEMS only, the title and content of that clause or subclause will say so. If that is not the case, the clause or subclause applies both to ME EQUIPMENT and to ME SYSTEMS, as relevant.

NOTE See also 4.2 of the general standard.

This particular standard does not apply to

- external limb prosthetic devices (use IEC 60601-2-523),
- electric wheelchairs (use ISO 7176 (all parts)),
- diagnostic imaging equipment (e.g. MRI, use IEC 60601-2-33), and
- personal care ROBOTS (use ISO 13482).

201.1.2 Object

Replacement:

The object of this particular standard is to establish particular BASIC SAFETY and ESSENTIAL PERFORMANCE requirements for MEDICAL ROBOTS that physically interact with a PATIENT with an IMPAIRMENT to support or perform REHABILITATION, ASSESSMENT, COMPENSATION or ALLEVIATION related to the PATIENT'S MOVEMENT FUNCTIONS.

201.1.3 Collateral standards

Addition:

This particular standard refers to those applicable collateral standards that are listed in Clause 2 of the general standard and Clause 201.2 of this particular standard.

¹ The general standard is IEC 60601-1:2005, IEC 60601-1:2005/AMD1:2012 and IEC 60601-1:2005/AMD2:2020, *Medical electrical equipment – Part 1: General requirements for basic safety and essential performance*.