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**Adjustable speed electrical power drive systems
Part 7-201: Generic interface and use of profiles for power drive systems –
Profile type 1 specification**

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CONTENTS

FOREWORD.....	14
INTRODUCTION.....	16
1 Scope.....	19
2 Normative references.....	19
3 Terms, definitions and abbreviated terms.....	19
3.1 Terms and definitions.....	19
3.2 Abbreviated terms.....	23
4 General.....	24
4.1 General considerations.....	24
4.2 Communication interface.....	24
4.3 Object dictionary.....	25
5 Data types.....	25
5.1 Standard data types.....	25
5.2 Record definitions.....	26
6 General object definitions.....	27
6.1 General.....	27
6.2 Communication parameter objects.....	27
6.3 Additional identification and information objects.....	28
6.3.1 Object 6402 _h : Motor type.....	28
6.3.2 Object 6403 _h : Motor catalogue number.....	29
6.3.3 Object 6404 _h : Motor manufacturer.....	29
6.3.4 Object 6405 _h : http motor catalogue address.....	30
6.3.5 Object 6406 _h : Motor calibration date.....	30
6.3.6 Object 6407 _h : Motor service period.....	31
6.3.7 Object 6503 _h : Drive catalogue number.....	31
6.3.8 Object 6505 _h : http drive catalogue address.....	32
7 Error codes and error behaviour.....	32
7.1 Error codes.....	32
7.2 Error behaviour.....	36
8 Controlling the power drive system.....	37
8.1 General.....	37
8.2 Finite state automaton.....	37
8.3 Modes of operation.....	40
8.4 Detailed object specifications.....	41
8.4.1 Object 6040 _h : Controlword.....	41
8.4.2 Object 6041 _h : Statusword.....	42
8.4.3 Object 603F _h : Error code.....	43
8.4.4 Object 6007 _h : Abort connection option code.....	44
8.4.5 Object 605A _h : Quick stop option code.....	45
8.4.6 Object 605B _h : Shutdown option code.....	46
8.4.7 Object 605C _h : Disable operation option code.....	46
8.4.8 Object 605D _h : Halt option code.....	47
8.4.9 Object 605E _h : Fault reaction option code.....	48
8.4.10 Object 6060 _h : Modes of operation.....	49
8.4.11 Object 6061 _h : Modes of operation display.....	50

8.4.12	Object 6502 _h : Supported drive modes	50
9	Factor group	51
9.1	General	51
9.2	Detailed object definitions	51
9.2.1	Object 608F _h : Position encoder resolution	51
9.2.2	Object 6090 _h : Velocity encoder resolution	52
9.2.3	Object 6091 _h : Gear ratio	53
9.2.4	Object 6092 _h : Feed constant	54
9.2.5	Object 607E _h : Polarity	55
10	Profile position mode	56
10.1	General information	56
10.2	Functional description	57
10.2.1	General	57
10.2.2	Single set-point	58
10.2.3	Set of set-points	59
10.3	General definitions	60
10.4	Use of controlword and statusword	60
10.5	Detailed object definitions	61
10.5.1	Object 607A _h : Target position	61
10.5.2	Object 607B _h : Position range limit	62
10.5.3	Object 607D _h : Software position limit	62
10.5.4	Object 607F _h : Max profile velocity	64
10.5.5	Object 6080 _h : Max motor speed	64
10.5.6	Object 6081 _h : Profile velocity	65
10.5.7	Object 6082 _h : End velocity	65
10.5.8	Object 6083 _h : Profile acceleration	66
10.5.9	Object 6084 _h : Profile deceleration	66
10.5.10	Object 6085 _h : Quick stop deceleration	67
10.5.11	Object 6086 _h : Motion profile type	67
10.5.12	Object 60A3 _h : Profile jerk use	68
10.5.13	Object 60A4 _h : Profile jerk	69
10.5.14	Object 60C4 _h : Max acceleration	70
10.5.15	Object 60C6 _h : Max deceleration	71
11	Homing mode	72
11.1	General information	72
11.2	Functional description	72
11.3	General definitions	73
11.3.1	Method 1: Homing on negative limit switch and index pulse	73
11.3.2	Method 2: Homing on positive limit switch and index pulse	73
11.3.3	Method 3 and 4: Homing on positive home switch and index pulse	73
11.3.4	Method 5 and 6: Homing on negative home switch and index pulse	74
11.3.5	Method 7 to 14: Homing on home switch and index pulse	74
11.3.6	Method 15 and 16: Reserved	75
11.3.7	Method 17 to 30: Homing without index pulse	75
11.3.8	Method 31 and 32: Reserved	76
11.3.9	Method 33 and 34: Homing on index pulse	76
11.3.10	Method 35: Homing on index pulse	76
11.3.11	Method 36: Homing with touch-probe	76
11.4	Use of controlword and statusword	76

11.5	Detailed object definitions	77
11.5.1	Object 607C _h : Home offset	77
11.5.2	Object 6098 _h : Homing method	78
11.5.3	Object 6099 _h : Homing speeds	79
11.5.4	Object 609A _h : Homing acceleration	80
11.5.5	Object 60B8 _h : Touch probe function	80
11.5.6	Object 60B9 _h : Touch probe status	82
11.5.7	Object 60BA _h : Touch probe pos1 pos value	82
11.5.8	Object 60BB _h : Touch probe pos1 neg value	83
11.5.9	Object 60BC _h : Touch probe pos2 pos value	83
11.5.10	Object 60BD _h : Touch probe pos2 neg value	84
12	Position control function	84
12.1	General information	84
12.2	Functional description	85
12.3	Detailed object definitions	87
12.3.1	Object 6062 _h : Position demand value	87
12.3.2	Object 6063 _h : Position actual internal value	87
12.3.3	Object 6064 _h : Position actual value	88
12.3.4	Object 6065 _h : Following error window	88
12.3.5	Object 6066 _h : Following error time out	89
12.3.6	Object 6067 _h : Position window	90
12.3.7	Object 6068 _h : Position window time	90
12.3.8	Object 60F4 _h : Following error actual value	91
12.3.9	Object 60FA _h : Control effort	91
12.3.10	Object 60FC _h : Position demand internal value	92
12.3.11	Object 60F2 _h : Positioning option code	92
13	Interpolated position mode	94
13.1	General information	94
13.2	Functional description	95
13.2.1	General	95
13.2.2	Linear interpolated position mode with several axes	96
13.2.3	Buffer strategies for the interpolated position mode	97
13.2.4	Interpolated position mode FSA	98
13.3	General definitions	99
13.4	Use of controlword and statusword	99
13.5	Detailed object definitions	100
13.5.1	Object 60C0 _h : Interpolation sub mode select	100
13.5.2	Object 60C1 _h : Interpolation data record	101
13.5.3	Object 60C2 _h : Interpolation time period	102
13.5.4	Object 60C4 _h : Interpolation data configuration	103
14	Profile velocity mode	105
14.1	General information	105
14.2	Functional description	106
14.3	General definitions	107
14.4	Use of controlword and statusword	107
14.5	Detailed object definitions	108
14.5.1	Object 6069 _h : Velocity sensor actual value	108
14.5.2	Object 606A _h : Sensor selection code	108
14.5.3	Object 606B _h : Velocity demand value	109

14.5.4	Object 606C _h : Velocity actual value	110
14.5.5	Object 606D _h : Velocity window	110
14.5.6	Object 606E _h : Velocity window time	111
14.5.7	Object 606F _h : Velocity threshold	111
14.5.8	Object 6070 _h : Velocity threshold time	112
14.5.9	Object 60FF _h : Target velocity	112
14.5.10	Object 60F8 _h : Max slippage	113
15	Profile torque mode	113
15.1	General information	113
15.2	Functional description	113
15.3	General definitions	114
15.4	Use of controlword and statusword	114
15.5	Detailed object definitions	115
15.5.1	Object 6071 _h : Target torque	115
15.5.2	Object 6072 _h : Max torque	116
15.5.3	Object 6073 _h : Max current	116
15.5.4	Object 6074 _h : Torque demand	117
15.5.5	Object 6075 _h : Motor rated current	117
15.5.6	Object 6076 _h : Motor rated torque	118
15.5.7	Object 6077 _h : Torque actual value	118
15.5.8	Object 6078 _h : Current actual value	119
15.5.9	Object 6079 _h : DC link circuit voltage	119
15.5.10	Object 6087 _h : Torque slope	120
15.5.11	Object 6088 _h : Torque profile type	120
16	Velocity mode	121
16.1	General information	121
16.2	Functional description	122
16.2.1	Velocity limit function	122
16.2.2	Ramp function	122
16.2.3	Velocity control function	122
16.2.4	Factor function	122
16.3	General definitions	123
16.4	Use of controlword and statusword	123
16.5	Detailed object definitions	124
16.5.1	Object 6042 _h : vI target velocity	124
16.5.2	Object 6043 _h : vI velocity demand	125
16.5.3	Object 6044 _h : vI velocity actual value	125
16.5.4	Object 6046 _h : vI velocity min max amount	126
16.5.5	Object 6049 _h : vI velocity deceleration	127
16.5.6	Object 6048 _h : vI velocity acceleration	128
16.5.7	Object 604A _h : vI velocity quick stop	130
16.5.8	Object 604B _h : vI set-point factor	131
16.5.9	Object 604C _h : vI dimension factor	132
17	Cyclic synchronous position mode	133
17.1	General information	133
17.2	Functional description	134
17.3	Use of controlword and statusword	135
17.4	Detailed object definitions	136
17.4.1	Object 60B0 _h : Position offset	136

17.4.2	Object 60B1 _h : Velocity offset.....	136
17.4.3	Object 60B2 _h : Torque offset.....	137
18	Cyclic synchronous velocity mode.....	137
18.1	General information.....	137
18.2	General definitions.....	138
18.3	Functional description.....	138
18.4	Use of controlword and statusword.....	139
19	Cyclic synchronous torque mode.....	140
19.1	General information.....	140
19.2	General definitions.....	140
19.3	Functional description.....	140
19.4	Use of controlword and statusword.....	141
20	Optional application FE.....	141
20.1	General.....	141
20.2	Object 60FD _h : Digital inputs.....	141
20.3	Object 60FE _h : Digital outputs.....	142
	Bibliography.....	144
	Figure 1 – Structure of IEC 61800-7.....	18
	Figure 2 – Value definition.....	27
	Figure 3 – Remote and local control.....	37
	Figure 4 – Power drive system finite state automaton.....	38
	Figure 5 – Relation between different value parameters.....	41
	Figure 6 – Value definition.....	41
	Figure 7 – Value definition.....	42
	Figure 8 – Value definition.....	50
	Figure 9 – Value definition.....	56
	Figure 10 – Trajectory generator and position control function.....	56
	Figure 11 – Trajectory generator for profile position mode.....	57
	Figure 12 – Set-point example.....	58
	Figure 13 – Handshaking procedure for the single set-point method.....	58
	Figure 14 – Handshaking procedure for the set of set-points method.....	59
	Figure 15 – Set-point handling for two set-points.....	59
	Figure 16 – Controlword for profile position (pp) mode.....	60
	Figure 17 – Statusword for profile position (pp) mode.....	61
	Figure 18 – Velocity/time diagram with jerk positions.....	69
	Figure 19 – Homing mode function.....	72
	Figure 20 – Homing on negative limit switch and index pulse.....	73
	Figure 21 – Homing on positive limit switch and index pulse.....	73
	Figure 22 – Homing on positive home switch and index pulse.....	74
	Figure 23 – Homing on negative home switch and index pulse.....	74
	Figure 24 – Homing on home switch and index pulse – positive initial motion.....	75
	Figure 25 – Homing on home switch and index pulse – negative initial motion.....	75
	Figure 26 – Homing on positive home switch.....	76

Figure 27 – Homing on index pulse	76
Figure 28 – Controlword for homing mode	76
Figure 29 – Statusword for homing mode	77
Figure 30 – Home offset definition	77
Figure 31 – Position control function	85
Figure 32 – Following error (functional overview)	85
Figure 33 – Position reached (functional overview)	86
Figure 34 – Position reached (definitions)	86
Figure 35 – Following error (definitions)	87
Figure 36 – Object structure	92
Figure 37 – Interpolation controller	95
Figure 38 – Interpolated position mode for two axes	96
Figure 39 – Linear interpolation for one axis	97
Figure 40 – Input buffer organisation	98
Figure 41 – Input buffer examples	98
Figure 42 – Interpolated position mode FSA	99
Figure 43 – Controlword for interpolated position mode	99
Figure 44 – Statusword for interpolated position mode	100
Figure 45 – Profile velocity mode	107
Figure 46 – Controlword for profile velocity mode	107
Figure 47 – Statusword for profile velocity mode	108
Figure 48 – Structure of the profile torque mode	114
Figure 49 – Controlword for profile torque mode	114
Figure 50 – Statusword for profile torque mode	115
Figure 51 – Velocity mode with all objects	121
Figure 52 – Velocity mode with mandatory objects only	121
Figure 53 – Velocity profile	122
Figure 54 – Factor function	122
Figure 55 – Reverse factor function	123
Figure 56 – Controlword for profile velocity mode	123
Figure 57 – Usage of controlword bits in velocity mode	124
Figure 58 – Statusword for profile velocity mode	124
Figure 59 – Transfer characteristic of v/ velocity min max amount	126
Figure 60 – Transfer characteristic of the velocity deceleration	127
Figure 61 – Transfer characteristic of the velocity acceleration	129
Figure 62 – Transfer characteristic of the quick stop deceleration	130
Figure 63 – Cyclic synchronous position mode overview	134
Figure 64 – Cyclic synchronous position control function	135
Figure 65 – Statusword for profile cyclic synchronous position mode	135
Figure 66 – Cyclic synchronous velocity mode overview	138
Figure 67 – Cyclic synchronous velocity control function	139
Figure 68 – Statusword for profile cyclic synchronous velocity mode	139
Figure 69 – Cyclic synchronous torque mode overview	140

Figure 70 – Cyclic synchronous torque control function.....	141
Figure 71 – Statusword for profile cyclic synchronous torque mode	141
Figure 72 – Object structure	142
Figure 73 – Object structure	142
Table 1 – List of used data types	26
Table 2 – Interpolated time period	26
Table 3 – Interpolated data configuration	26
Table 4 – vl velocity acceleration/deceleration	26
Table 5 – Object description	27
Table 6 – Entry description	28
Table 7 – Value definition	28
Table 8 – Object description	29
Table 9 – Entry description	29
Table 10 – Object description	29
Table 11 – Entry description	29
Table 12 – Object description	30
Table 13 – Entry description	30
Table 14 – Object description	30
Table 15 – Entry description	30
Table 16 – Object description	31
Table 17 – Entry description	31
Table 18 – Object description	31
Table 19 – Entry description	31
Table 20 – Object description	32
Table 21 – Entry description	32
Table 22 – Object description	32
Table 23 – Entry description	32
Table 24 – Error codes	33
Table 25 – FSA states and supported functions	38
Table 26 – Transition events and actions	39
Table 27 – Command coding	41
Table 28 – Object description	42
Table 29 – Entry description	42
Table 30 – State coding	42
Table 31 – Object description	43
Table 32 – Entry description	43
Table 33 – Object description	44
Table 34 – Entry description	44
Table 35 – Value definition	44
Table 36 – Object description	44
Table 37 – Entry description	45
Table 38 – Value definition	45

Table 39 – Object description	45
Table 40 – Entry description	46
Table 41 – Value definition	46
Table 42 – Object description	46
Table 43 – Entry description	46
Table 44 – Value definition	47
Table 45 – Object description	47
Table 46 – Entry description	47
Table 47 – Value definition	47
Table 48 – Object description	48
Table 49 – Entry description	48
Table 50 – Value definition	48
Table 51 – Object description	48
Table 52 – Entry description	49
Table 53 – Value definition	49
Table 54 – Object description	49
Table 55 – Entry description	50
Table 56 – Object description	50
Table 57 – Entry description	50
Table 58 – Object description	51
Table 59 – Entry description	51
Table 60 – Object description	52
Table 61 – Entry description	52
Table 62 – Object description	53
Table 63 – Entry description	53
Table 64 – Object description	54
Table 65 – Entry description	54
Table 66 – Object description	55
Table 67 – Entry description	55
Table 68 – Object description	56
Table 69 – Entry description	56
Table 70 – Definition of bit 4, bit 5, and bit 9	60
Table 71 – Definition of bit 6 and bit 8	60
Table 72 – Definition of bit 10, bit 12, and bit 13	61
Table 73 – Object description	61
Table 74 – Entry description	61
Table 75 – Object description	62
Table 76 – Entry description	62
Table 77 – Object description	63
Table 78 – Entry description	63
Table 79 – Object description	64
Table 80 – Entry description	64
Table 81 – Object description	64

Table 82 – Entry description	65
Table 83 – Object description	65
Table 84 – Entry description	65
Table 85 – Object description	66
Table 86 – Entry description	66
Table 87 – Object description	66
Table 88 – Entry description	66
Table 89 – Object description	67
Table 90 – Entry description	67
Table 91 – Object description	67
Table 92 – Entry description	67
Table 93 – Value definition	68
Table 94 – Object description	68
Table 95 – Entry description	68
Table 96 – Object description	68
Table 97 – Entry description	69
Table 98 – Value assignments	69
Table 99 – Object description	69
Table 100 – Entry description	70
Table 101 – Object description	71
Table 102 – Entry description	71
Table 103 – Object description	71
Table 104 – Entry description	71
Table 105 – Definition of bit 4 and bit 8	77
Table 106 – Definition of bit 10, bit 11, and bit 13	77
Table 107 – Object description	78
Table 108 – Entry description	78
Table 109 – Value definition	78
Table 110 – Object description	78
Table 111 – Entry description	79
Table 112 – Object description	79
Table 113 – Entry description	79
Table 114 – Object description	80
Table 115 – Entry description	80
Table 116 – Value definition	81
Table 117 – Object description	81
Table 118 – Entry description	81
Table 119 – Value definition	82
Table 120 – Object description	82
Table 121 – Entry description	82
Table 122 – Object description	83
Table 123 – Entry description	83
Table 124 – Object description	83

Table 125 – Entry description	83
Table 126 – Object description	84
Table 127 – Entry description	84
Table 128 – Object description	84
Table 129 – Entry description	84
Table 130 – Object description	87
Table 131 – Entry description	87
Table 132 – Object description	88
Table 133 – Entry description	88
Table 134 – Object description	88
Table 135 – Entry description	88
Table 136 – Object description	89
Table 137 – Entry description	89
Table 138 – Object description	89
Table 139 – Entry description	89
Table 140 – Object description	90
Table 141 – Entry description	90
Table 142 – Object description	90
Table 143 – Entry description	91
Table 144 – Object description	91
Table 145 – Entry description	91
Table 146 – Object description	91
Table 147 – Entry description	92
Table 148 – Object description	92
Table 149 – Entry description	92
Table 150 – Value definition for bit 0 and bit 1	93
Table 151 – Value definition for bit 2 and bit 3	93
Table 152 – Value definition for bit 4 and bit 5	93
Table 153 – Object description	94
Table 154 – Entry description	94
Table 155 – Position calculation in interpolated position mode for several axes	96
Table 156 – FSA states and supported functions	99
Table 157 – Transition events and actions	99
Table 158 – Definition of bit 4 and bit 8.....	100
Table 159 – Definition of bit 10 and bit 12.....	100
Table 160 – Value definition	100
Table 161 – Object description	101
Table 162 – Entry description	101
Table 163 – Object description	101
Table 164 – Entry description	102
Table 165 – Object description	103
Table 166 – Entry description	103
Table 167 – Object description	104

Table 168 – Entry description	104
Table 169 – Definition of bit 8	107
Table 170 – Definition of bit 10, bit 12, and bit 13	108
Table 171 – Object description	108
Table 172 – Entry description	108
Table 173 – Value definition	109
Table 174 – Object description	109
Table 175 – Entry description	109
Table 176 – Object description	109
Table 177 – Entry description	110
Table 178 – Object description	110
Table 179 – Entry description	110
Table 180 – Object description	110
Table 181 – Entry description	111
Table 182 – Object description	111
Table 183 – Entry description	111
Table 184 – Object description	111
Table 185 – Entry description	112
Table 186 – Object description	112
Table 187 – Entry description	112
Table 188 – Object description	112
Table 189 – Entry description	113
Table 190 – Object description	113
Table 191 – Entry description	113
Table 192 – Definition of bit 8	115
Table 193 – Definition of bit 10	115
Table 194 – Object description	115
Table 195 – Entry description	115
Table 196 – Object description	116
Table 197 – Entry description	116
Table 198 – Object description	116
Table 199 – Entry description	116
Table 200 – Object description	117
Table 201 – Entry description	117
Table 202 – Object description	117
Table 203 – Entry description	117
Table 204 – Object description	118
Table 205 – Entry description	118
Table 206 – Object description	118
Table 207 – Entry description	118
Table 208 – Object description	119
Table 209 – Entry description	119
Table 210 – Object description	119

Table 211 – Entry description	119
Table 212 – Object description	120
Table 213 – Entry description	120
Table 214 – Value definition	120
Table 215 – Object description	120
Table 216 – Entry description	121
Table 217 – Definition of bit 4, bit 5, bit 6, and bit 8	123
Table 218 – Object description	124
Table 219 – Entry description	124
Table 220 – Object description	125
Table 221 – Entry description	125
Table 222 – Object description	125
Table 223 – Entry description	126
Table 224 – Object description	126
Table 225 – Entry description	127
Table 226 – Object description	128
Table 227 – Entry description	128
Table 228 – Object description	129
Table 229 – Entry description	129
Table 230 – Object description	130
Table 231 – Entry description	131
Table 232 – Object description	131
Table 233 – Entry description	132
Table 234 – Object description	133
Table 235 – Entry description	133
Table 236 – Definition of bit 10, bit 12, and bit 13	135
Table 237 – Object description	136
Table 238 – Entry description	136
Table 239 – Object description	136
Table 240 – Entry description	137
Table 241 – Object description	137
Table 242 – Entry description	137
Table 243 – Definition of bit 10, bit 12, and bit 13	139
Table 244 – Definition of bit 10, bit 12, and bit 13	141
Table 245 – Value definition	142
Table 246 – Object description	142
Table 247 – Entry description	142
Table 248 – Value definition	143
Table 249 – Object description	143
Table 250 – Entry description	143

INTERNATIONAL ELECTROTECHNICAL COMMISSION

ADJUSTABLE SPEED ELECTRICAL POWER DRIVE SYSTEMS –

Part 7-201: Generic interface and use of profiles for power drive systems – Profile type 1 specification

FOREWORD

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The text of this standard is based on the following documents:

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22G/184/FDIS	22G/192/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of the IEC 61800 series, under the general title *Adjustable speed electrical power drive systems*, can be found on the IEC website.

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- reconfirmed;
- withdrawn;
- replaced by a revised edition, or
- amended.

A bilingual version of this publication may be issued at a later date.

INTRODUCTION

The IEC 61800 series is intended to provide a common set of specifications for adjustable speed electrical power drive systems.

IEC 61800-7 describes a generic interface between control systems and power drive systems. This interface can be embedded in the control system. The control system itself can also be located in the drive (sometimes known as "smart drive" or "intelligent drive").

A variety of physical interfaces is available (analogue and digital inputs and outputs, serial and parallel interfaces, fieldbuses and networks). Profiles based on specific physical interfaces are already defined for some application areas (e.g. motion control) and some device classes (e.g. standard drives, positioner). The implementations of the associated drivers and application programmers interfaces are proprietary and vary widely.

IEC 61800-7 defines a set of common drive control functions, parameters, and state machines or description of sequences of operation to be mapped to the profiles.

IEC 61800-7 provides a way to access functions and data of a drive that is independent of the used drive profile and communication interface. The objective is a common drive model with generic functions and objects suitable to be mapped on different communication interfaces. This makes it possible to provide common implementations of motion control (or velocity control or drive control applications) in controllers without any specific knowledge of the drive implementation.

There are several reasons to define a generic interface:

For a drive device manufacturer

- Less effort to support system integrators
- Less effort to describe drive functions because of common terminology
- The selection of drives does not depend on availability of specific support

For a control device manufacturer

- No influence of bus technology
- Easy device integration
- Independent of a drive supplier

For a system integrator (builds modules, machines, plants etc.)

- Less integration effort for devices
- Only one understandable way of modeling
- Independent of bus technology

Much effort is needed to design a motion control application with several different drives and a specific control system. The tasks to implement the system software and to understand the functional description of the individual components may exhaust the project resources. In some cases, the drives do not share the same physical interface. Some control devices just support a single interface which will not be supported by a specific drive. On the other hand, the functions and data structures are specified with incompatibilities. It is up to the systems integrator to write interfaces to the application software to handle that which should not be his responsibility.

Some applications need device exchangeability or integration of new devices in an existing configuration. They are faced with different incompatible solutions. The efforts to adopt a solution to a drive profile and to manufacturer specific extensions may be unacceptable. This will reduce the degree of freedom to select a device best suited for this application to the selection of the unit which will be available for a specific physical interface and supported by the controller.

IEC 61800-7-1 is divided into a generic part and several annexes as shown in Figure 1. The drive profile types for CiA 402¹, CIP Motion^{TM2}, PROFIdrive³ and SERCOS Interface^{TM4} are mapped to the generic interface in the corresponding annex. The annexes have been submitted by open international network or fieldbus organizations which are responsible for the content of the related annex and use of the related trademarks.

This part of IEC 61800-7 specifies the profile type 1 (CiA 402).

The profile types 2, 3 and 4 are specified in IEC 61800-7-202, IEC 61800-7-203 and IEC 61800-7-204.

IEC 61800-7-301, IEC 61800-7-302, IEC 61800-7-303 and IEC 61800-7-304 specify how the profile types 1, 2, 3 and 4 are mapped to different network technologies (such as CANopen⁵, EtherCAT^{TM6}, Ethernet Powerlink^{TM7}, DeviceNet^{TM8}, ControlNet^{TM9}, EtherNet/IP^{TM10}, PROFIBUS¹¹, PROFINET¹² and SERCOS Interface).

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- 1 CiA 402 is a trade name of CAN in Automation, e.V. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name CiA 402.
 - 2 CIP MotionTM is a trade name of Open DeviceNet Vendor Association, Inc. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name CIP MotionTM. Use of the trade name CIP MotionTM requires permission of Open DeviceNet Vendor Association, Inc.
 - 3 PROFIdrive is a trade name of PROFIBUS International. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name PROFIdrive. Use of the trade name PROFIdrive requires permission of PROFIBUS International.
 - 4 SERCOSTM and SERCOS InterfaceTM are trade names of SERCOS International e.V. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name SERCOS and SERCOS interface. Use of the trade name SERCOS and SERCOS interface requires permission of the trade name holder.
 - 5 CANopen is an acronym for Controller Area Network *open* and is used to refer to EN 50325-4.
 - 6 EtherCATTM is a trade name of Beckhoff, Verl. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name EtherCATTM. Use of the trade name EtherCATTM requires permission of the trade name holder.
 - 7 Ethernet PowerlinkTM is a trade name of B&R, control of trade name use is given to the non profit organisation EPSG. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name Ethernet PowerlinkTM. Use of the trade name Ethernet PowerlinkTM requires permission of the trade name holder.
 - 8 DeviceNetTM is a trade name of Open DeviceNet Vendor Association, Inc. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name DeviceNetTM. Use of the trade name DeviceNetTM requires permission of Open DeviceNet Vendor Association, Inc.
 - 9 ControlNetTM is a trade name of ControlNet International, Ltd. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name ControlNetTM. Use of the trade name ControlNetTM requires permission of ControlNet International, Ltd.
 - 10 EtherNet/IPTM is a trade name of ControlNet International, Ltd. and Open DeviceNet Vendor Association, Inc. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name EtherNet/IPTM. Use of the trade name EtherNet/IPTM requires permission of either ControlNet International, Ltd. or Open DeviceNet Vendor Association, Inc.
 - 11 PROFIBUS is a trade name of PROFIBUS International. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name PROFIBUS. Use of the trade name PROFIBUS requires permission of PROFIBUS International.
 - 12 PROFINET is a trade name of PROFIBUS International. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name PROFINET. Use of the trade name PROFINET requires permission of PROFIBUS International.

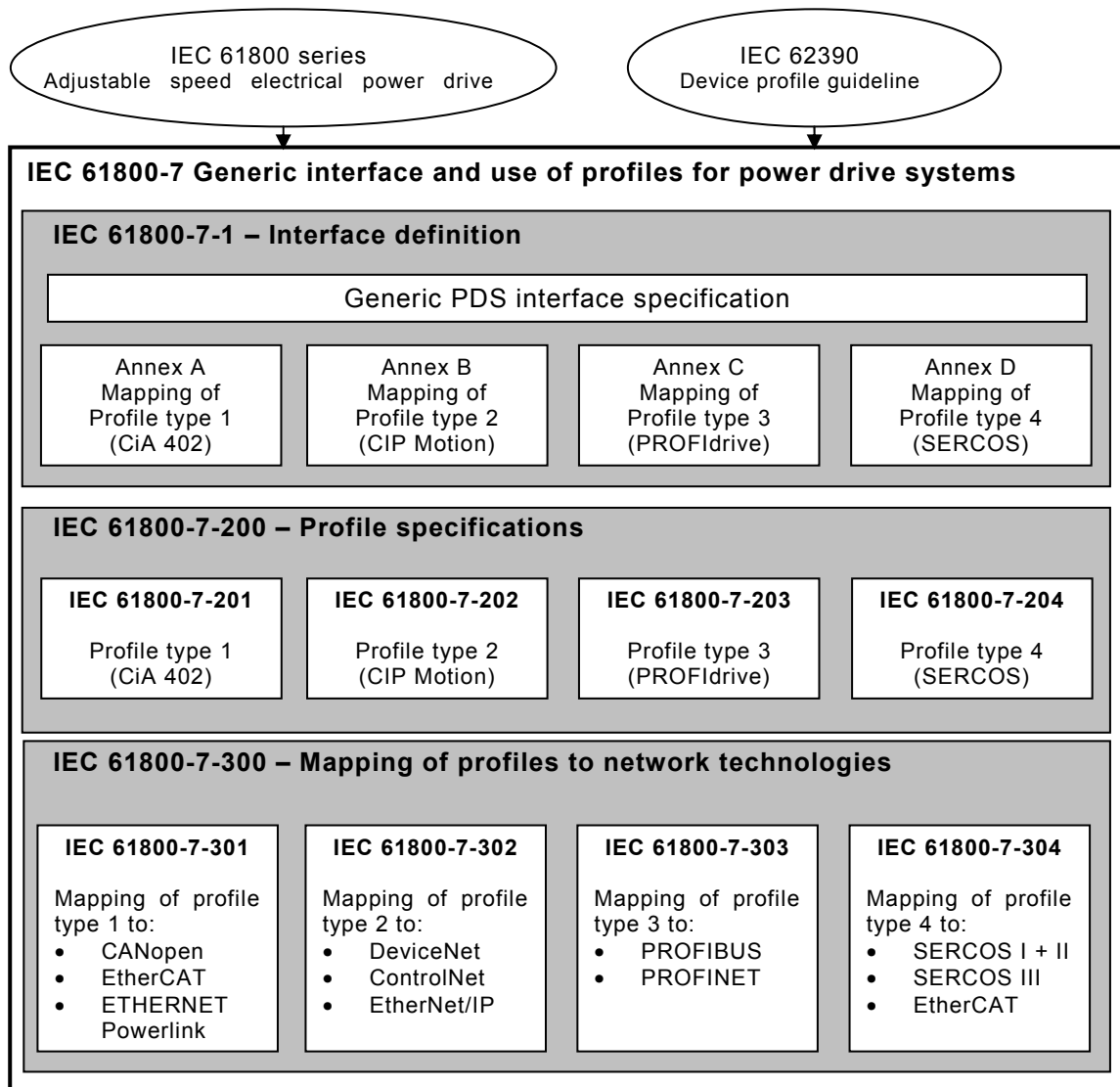


Figure 1 – Structure of IEC 61800-7

ADJUSTABLE SPEED ELECTRICAL POWER DRIVE SYSTEMS –

Part 7-201: Generic interface and use of profiles for power drive systems – Profile type 1 specification

1 Scope

IEC 61800-7 specifies profiles for Power Drive Systems (PDS) and their mapping to existing communication systems by use of a generic interface model.

The functions specified in this part of IEC 61800-7 are not intended to ensure functional safety. This requires additional measures according to the relevant standards, agreements and laws.

This part of IEC 61800-7 specifies profile type 1 for Power Drive Systems (PDS). Profile type 1 can be mapped onto different communication network technologies.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 61800-7 (all parts), *Adjustable speed electrical power drive systems – Generic interface and use of profiles for power drive systems*

IEC 61800-7-301, *Adjustable speed electrical power drive systems – Part 7-301: Generic interface and use of profiles for power drive systems – Mapping of profile type 1 to network technologies*

EN 50325-4, *Industrial communications subsystem based on ISO 11898 (CAN) for controller-device interfaces – Part 4: CANopen*