



BSI Standards Publication

Road vehicles — Human performance and state in the context of automated driving

Part 2: Considerations in designing experiments to investigate transition processes

National foreword

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**Road vehicles — Human performance
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**Part 2:
Considerations in designing
experiments to investigate
transition processes**

*Véhicules routiers — État et performance humaine dans le contexte
de la conduite automatisée —*

*Partie 2: Principes expérimentaux pour étudier les processus
de transition*



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Foreword

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The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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This document was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 39, *Ergonomics*.

A list of all parts in the ISO 21959 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

Although automation technology is advancing at a rapid pace, the majority of automated driving levels (as defined by SAE J3016, 2016^[1]) still require a human to fulfil specific remaining (driving related) tasks. The safety-critical human's task is the takeover task in transition from a higher level to a lower level of automated driving. Researchers and developers continue to seek system design and human machine interface improvements for better takeover performance. Researchers face a challenge in understanding the limitations of a human's ability to perform the takeover task, which involves different human factors. Developers work to evaluate systems to see whether the takeover process is effective at minimum risk in specific scenarios. There are a wide variety of experiments to evaluate takeover performance in transition for many different purposes. This document contains information to consider in the takeover scenario, some of which is still under investigation, in order to help readers design experiments to evaluate takeover performance and design appropriate experiments.

Road vehicles — Human performance and state in the context of automated driving —

Part 2:

Considerations in designing experiments to investigate transition processes

1 Scope

This document focuses on system-initiated and human-initiated transitions (Clause 6) from a higher level to a lower level of automated driving. Human factors and system factors that can influence takeover performance are included (Clauses 7 and 8). Although some are still under investigation, there is a need to appropriately set these factors as variables to better understand their effects or to better control/eliminate their influence. This approach will aid research design by ensuring that important factors are considered and support consistency across studies enabling meaningful comparisons of findings. This document also includes information on considerations in test scenario design (Clause 9), common measures for human takeover performance (Clause 10) and considerations in choosing a testing environment (Clause 11) to help readers design experiments comparable to other studies.

2 Normative references

There are no normative references in this document.

3 Terms and definitions

No terms and definitions are listed in this document.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform, available at <https://www.iso.org/obp>
- IEC Electropedia, available at <http://www.electropedia.org/>

4 List of Acronyms

DDT	Dynamic Driving Task
DMS	Driver Monitor System
ECG	Electrocardiogram
EEG	Electroencephalogram
HMI	Human-Machine Interface
KSS	Karolinska Sleepiness Scale
MRM	Minimal Risk Manoeuvre
NDRT	Non-driving Related Task