

ASME BTH-1–2023
(Revision of ASME BTH-1–2020)

Design of Below-the-Hook Lifting Devices

AN AMERICAN NATIONAL STANDARD



The American Society of
Mechanical Engineers

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FOREWORD

There have been many formal requests for interpretation of the limited structural design criteria stated within ASME B30.20, Below-the-Hook Lifting Devices, a safety standard. As a consequence, industry has for quite some time expressed a need for a comprehensive design standard for below-the-hook lifting devices that would complement the safety requirements of ASME B30.20. All editions of ASME B30.20 have included structural design criteria oriented toward the industrial manufacturing community requiring a minimum design factor of 3, based on the yield strength of the material; recent editions have also included design criteria for the fatigue failure mode. However, members of the construction community expressed the need for design criteria more suitable to their operating conditions, including a lower design factor, and the necessity to address other failure modes such as fracture, shear, and buckling, and design topics such as impact and fasteners.

A Design Task Group was created in 1997 to begin work on a design standard as a companion document to ASME B30.20. The ASME BTH Standards Committee on the Design of Below-the-Hook Lifting Devices was formed out of the Design Task Group and held its organizational meeting on December 5, 1999.

ASME BTH-1-2005, Design of Below-the-Hook Lifting Devices, contained five chapters: Scope and Definitions, Lifter Classifications, Structural Design, Mechanical Design, and Electrical Components. This Standard, intended for general industry and construction, set forth two design categories for lifting devices based on the magnitude and variation of loading, and operating and environmental conditions. The two design categories provided different design factors for determining allowable static stress limits. Five Service Classes based on lifting cycles were provided. The Service Class establishes allowable stress range values for lifting device structural members and design parameters for mechanical components. ASME BTH-1-2005 was approved by the American National Standards Institute (ANSI) on October 18, 2005.

ASME BTH-1-2008 incorporated editorial revisions and two new mechanical design sections for grip ratio and vacuum lifting device design. ASME BTH-1-2008 was approved by ANSI on September 17, 2008.

ASME BTH-1-2011 incorporated revisions throughout the Standard and the addition of a new mechanical design section for fluid power systems. ASME BTH-1-2011 was approved by ANSI on September 23, 2011.

ASME BTH-1-2014 incorporated into Chapter 4 a section on lifting magnets. Other technical revisions included new requirements for fluid pressure control and electrical system guarding. Along with these technical changes, the non-mandatory Commentary for each chapter was moved to its own respective Nonmandatory Appendix. ASME BTH-1-2014 was approved by ANSI on June 24, 2014.

ASME BTH-1-2017 included the addition of Chapter 6: Lifting Magnet Design, an accompanying Nonmandatory Appendix with commentary for the new chapter, and other revisions. Following the approval by the ASME BTH Standards Committee, ANSI approved ASME BTH-1-2017 on January 6, 2017.

ASME BTH-1-2020 included clarification of the requirement to establish the rated load of a lifting device by calculation, incorporation of ASME B30.30-2019 into the rope requirements in Chapter 4, improvements based on user input, revision of Chapter 5 title to Electrical Design, and consideration for load blocks and lifting attachments. Following the approval by the ASME BTH Standards Committee, ANSI approved this edition as an American National Standard, with the new designation ASME BTH-1-2020, on December 9, 2020.

This edition of ASME BTH-1 includes revision of the terms “lifter” to “lifting device” and “magnet lifter” to “lifting magnet,” updating of the fatigue design provisions, clarification of the effective shear area for tubular members, addition of an equation for the calculation of the tensile stress area of a threaded fastener, addition of a reference to ASME B30.1 for fluid power cylinders used in lifting devices, and expansion of the provisions for vacuum lifting devices. Following the approval by the ASME BTH Standards Committee, ANSI approved this edition as an American National Standard, with the new designation ASME BTH-1-2023, on June 16, 2023.

ASME BTH STANDARDS COMMITTEE

Design of Below-the-Hook Lifting Devices

(The following is the roster of the committee at the time of approval of this Standard.)

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Revisions and Errata. The committee processes revisions to this Standard on a continuous basis to incorporate changes that appear necessary or desirable as demonstrated by the experience gained from the application of the Standard. Approved revisions will be published in the next edition of the Standard.

In addition, the committee may post errata on the committee web page. Errata become effective on the date posted. Users can register on the committee web page to receive e-mail notifications of posted errata.

This Standard is always open for comment, and the committee welcomes proposals for revisions. Such proposals should be as specific as possible, citing the paragraph number(s), the proposed wording, and a detailed description of the reasons for the proposal, including any pertinent background information and supporting documentation.

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ASME BTH-1-2023 SUMMARY OF CHANGES

Following approval by the ASME BTH Committee and ASME, and after public review, ASME BTH-1-2023 was approved by the American National Standards Institute on June 16, 2023.

ASME BTH-1-2023 includes the following changes identified by a margin note, **(23)**.

<i>Page</i>	<i>Location</i>	<i>Change</i>
1	Chapter 1	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
2	1-5.1	(1) Definition of <i>below-the-hook lifting device</i> (<i>lifting device, lifter</i>) revised (2) Definition of <i>nonmandatory appendix</i> added
3	1-5.3	Definitions of <i>bystander, fall zone, manual vacuum lifting device, mechanical vacuum lifting device, powered vacuum lifting device, precharged vacuum lifting device, safety-trained person, and self-priming vacuum lifting device</i> added
4	1-5.5	(1) Definitions of <i>air gap, magnet duty cycle, and maximum energy product</i> revised (2) The following terms revised: <i>electrically controlled permanent magnet</i> to <i>electrically controlled permanent lifting magnet</i> and <i>manually controlled permanent magnet</i> to <i>manually controlled permanent lifting magnet</i>
5	Figure 1-5.5-1	Title revised
6	1-6.1	Definitions of d_b , n , and p added
8	1-6.3	Note revised
9	1-7	Updated
10	Chapter 2	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
11	Chapter 3	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
15	3-2.3.7	Added
17	3-3.2	(1) Equations (3-45) and (3-46) added, and subsequent equations redesignated (2) Definition of A_s revised (3) Definitions of d_b , m , n , and p added
23	Table 3-4-1	Revised in its entirety
38	Chapter 4	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
38	4-2.2	Revised
38	4-2.3	Revised
38	4-2.6	Title revised
38	4-2.7	(1) Added, and subsequent paragraph redesignated (2) Former Figure 4-2.7-1 redesignated as Figure 4-2.8-1
39	4-3.2	Revised
44	4-10.2	Revised in its entirety
45	Table 4-10.2-1	Added

<i>Page</i>	<i>Location</i>	<i>Change</i>
46	4-11.2	Revised in its entirety
47	Chapter 5	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
49	5-6.3	Terms <i>magnet</i> and <i>electromagnet</i> revised to <i>lifting magnet</i> and <i>lifting electromagnet</i> , respectively
50	Chapter 6	(1) Terms <i>magnet</i> and <i>material handling magnet</i> revised to <i>lifting magnet</i> throughout (2) Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
54	Nonmandatory Appendix A	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
56	A-5.3	Added
56	A-7	Updated
58	Nonmandatory Appendix B	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
60	Nonmandatory Appendix C	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
62	C-2.2	In third paragraph, last AISC reference updated
64	C-2.6	AISC reference updated
65	C-3.1	In second paragraph, last two AISC references updated
67	C-4.1	AISC reference updated
68	C-4.4	AISC reference updated
68	C-4.5	AISC reference updated
68	C-4.6	AISC reference updated
69	Nonmandatory Appendix D	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
71	D-10.2	Revised in its entirety
72	D-11.2	(1) First paragraph added (2) Second paragraph revised
73	Nonmandatory Appendix E	Terms <i>lifter</i> and <i>device</i> revised to <i>lifting device</i> throughout
75	Nonmandatory Appendix F	Term <i>magnet</i> revised to <i>lifting magnet</i> throughout

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Chapter 1

Scope, Definitions, and References

(23)

1-1 PURPOSE

This Standard sets forth design criteria for ASME B30.20, Below-the-Hook Lifting Devices. This Standard serves as a guide to designers, manufacturers, purchasers, and users of below-the-hook lifting devices.

1-2 SCOPE

This Standard provides minimum structural, mechanical, and electrical design criteria for ASME B30.20, Below-the-Hook Lifting Devices.

The provisions in this Standard apply to the design or modification of below-the-hook lifting devices. Compliance with requirements and criteria that may be unique to specialized industries and environments is outside the scope of this Standard.

Lifting devices designed to this Standard shall comply with ASME B30.20, Below-the-Hook Lifting Devices. ASME B30.20 includes provisions that apply to the marking, construction, installation, inspection, testing, maintenance, and operation of below-the-hook lifting devices.

The provisions defined in this Standard address the most common and broadly applicable aspects of the design of below-the-hook lifting devices. A qualified person shall determine the appropriate methods to be used to address design issues that are not explicitly covered in the Standard so as to provide design factors and/or performance consistent with the intent of this Standard.

1-3 NEW AND EXISTING LIFTING DEVICES

The effective date of this Standard shall be one year after its date of issuance. Lifting devices manufactured after the effective date shall conform to the requirements of this Standard.

When a lifting device is being modified, its design shall be reviewed relative to this Standard, and the need to meet this Standard shall be evaluated by the manufacturer or a qualified person.

1-4 GENERAL REQUIREMENTS

1-4.1 Design Responsibility

Lifting devices shall be designed by, or under the direct supervision of, a qualified person.

1-4.2 Units of Measure

A dual unit format is used. Values are given in U.S. Customary units as the primary units followed by the International System of Units (SI) in parentheses as the secondary units. The values stated in U.S. Customary units are to be regarded as the standard. The SI units in the text have been directly (softly) converted from U.S. Customary units.

1-4.3 Design Criteria

All below-the-hook lifting devices shall be designed for specified rated loads, load geometry, Design Category (see [section 2-2](#)), and Service Class (see [section 2-3](#)). Resolution of loads into forces and stress values affecting structural members, mechanical components, and connections shall be performed by an accepted analysis method. The rated load shall not be determined by a load test only.

1-4.4 Analysis Methods

The allowable stresses and stress ranges defined in this Standard are based on the assumption of analysis by classical strength of material methods (models), although other analysis methods may be used. The analysis techniques and models used by the qualified person shall accurately represent the loads, material properties, and lifting device geometry; stress values resulting from the analysis shall be of suitable form to permit correlation with the allowable stresses defined in this Standard.

1-4.5 Material

The design provisions of this Standard are based on the use of carbon, high-strength low-alloy, or heat-treated constructional alloy steel for structural members and many mechanical components. Other materials may be used, provided the design factors and fatigue life are equal to or greater than those required by this Standard.

All ferrous and nonferrous metal used in the fabrication of lifting device structural members and mechanical components shall be identified by an industry-wide or written proprietary specification.